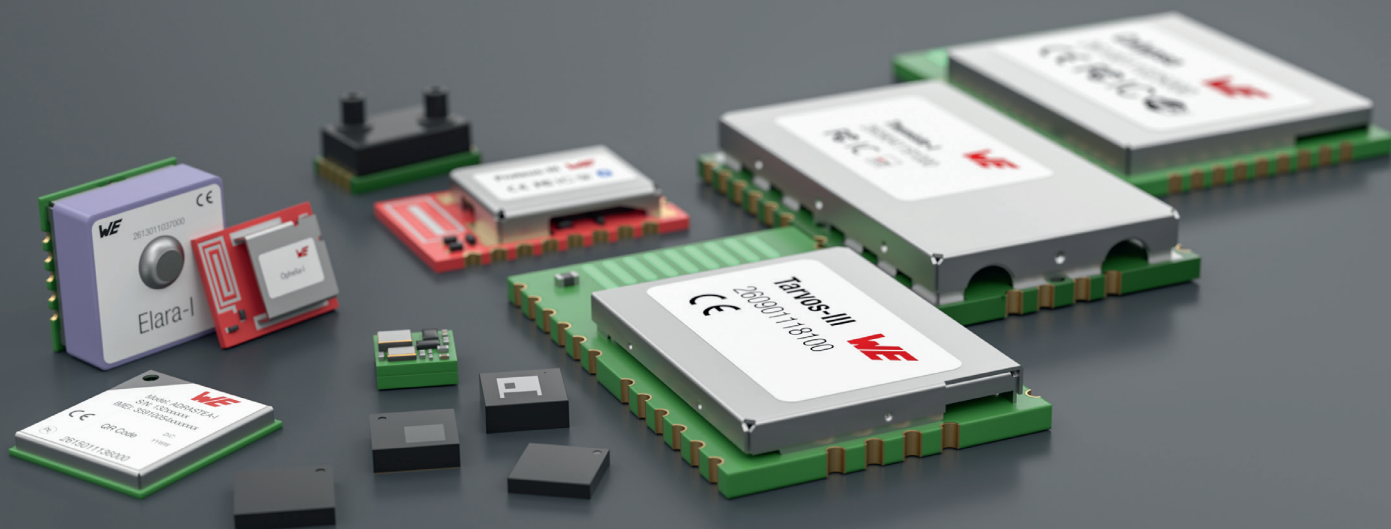




USER MANUAL

TARVOS-E

2609051181000

VERSION 2.14

JUNE 17, 2025

WÜRTH ELEKTRONIK MORE THAN YOU EXPECT

MUST READ

Check for firmware updates

Before using the product, make sure you use the most recent firmware version, data sheet, and user manual. This is especially important for Wireless Connectivity products that were not purchased directly from Würth Elektronik eiSos. A firmware update on these respective products may be required.

We strongly recommend including the possibility of a firmware update in the customer system design.

Revision history

Manual version	FW version	HW version	Notes	Date
2.14	3.3.0	2.2	Initial version of Tarvos-e. Corresponds to Tarvos-III FW 3.3.0 and Tarvos-III user manual 2.14.	June 2025

★ For firmware history see chapter `Firmware history`

Abbreviations

Abbreviation	Name	Description
ACK	Acknowledgement	Acknowledgement pattern confirming the reception of the transmitted data packet.
BDM	Business Development Manager	Support and sales contact person responsible for a limited sales area.
CS	Checksum	XOR checksum to check the correct transmission of the prepended Bytes.
CSMA-CA	Carrier Sense Multiple Access - Collision Avoidance	It is a network protocol that helps prevent data collisions by having devices check if the communication channel is free before transmitting.
DC	Duty Cycle	Transmission time in relation of one hour. 1 % means, channel is occupied for 36 seconds per hour.
ETA	Equipment Type Approval Certificate	It is an official document that certifies a device meets regulatory standards and is approved for use in a specific country or region.
0xhh [HEX]	Hexadecimal	All numbers beginning with 0x are stated as hexadecimal numbers. All other numbers are decimal, unless otherwise notified.
HIGH	High signal level	Signal level equals VDD.
LBT	Listen Before Talk	Check whether the channel is free before attempting to send a packet.
LNA	Low Noise Amplifier	Electronic module that amplifies weak signals while minimizing noise.
LOW	Low signal level	Signal levels equals 0 Volts.
LPM	Low Power Mode	Operation mode for reduced power consumption.
LRM	Long Range Mode	Transmit mode increasing the reception sensitivity, by using spreading and forward error correction.
LSB	Least Significant Bit	The Least Significant Bit (LSB) is the rightmost bit in a binary number
MSB	Most Significant Bit	The Most Significant Bit (MSB) is the leftmost bit in a binary number
PL	Payload	The real, non-redundant information in a frame / packet.
PSA	Polite Spectrum Access	Set of measures that allow for more flexible use of radio spectrum by devices.
RF	Radio Frequency	Describes everything relating to the wireless transmission.

UART	Universal Asynchronous Receiver Transmitter	The UART allows communicating with the module of a specific interface.
US	User settings	Any relation to a specific entry in the user settings is marked in a special font and can be found in the chapter 8.
VDD	Supply voltage	It refers to the positive voltage supplied to the power pin
WPC	Wireless Planning and Coordination	-

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Overview of helpful application notes

Application note ANR008 - Wireless Connectivity Software Development Kit

<http://www.we-online.com/ANR008>

To ease the integration of the Würth Elektronik eiSos radio modules into an application, Würth Elektronik eiSos offers the corresponding Software Development Kit (SDK) for most commonly used host processors. This SDK contains drivers and examples in C-code to communicate with the corresponding radio module. This application note shows which SDKs are available and describes how to download and use them.

Application note ANR010 - Range estimation

<http://www.we-online.com/ANR010>

This application note presents the two most used mathematical range estimation models, Friis and two ray ground reflection, and its implementation in the range estimation tool of the RED-EXPERT.

Application note ANR016 - Radio module migration guide

<http://www.we-online.com/ANR016>

Due to our long term availability policy Würth Elektronik eiSos offers beside radio modules with most recent technology and chipset still the predecessor modules. This application note describes what to consider when switching in between module generations.

1. Introduction

This manual is valid for Tarvos-e (2609051181000). The Tarvos-e module is designed to be compatible with the Tarvos-III in terms of protocol (RF and UART) and timings except for radio profile 3. However, the hardware platform differs, resulting in variations in the footprint and size of the module. Additionally, this module is exclusively available with the external antenna option.

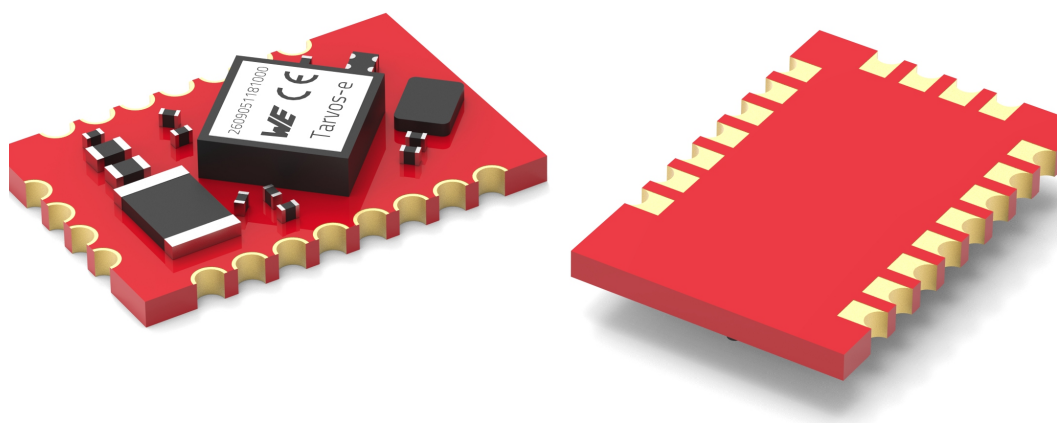


Figure 1: Tarvos-e

1.1. Operational description

The Tarvos-e is a radio module for wireless communication between devices, such as control systems, remote controls, sensors, etc. It offers several radio configurations, address modes and relieves the host system of radio-specific tasks such as

- checksum calculation,
- address resolution and
- repetition of unacknowledged telegrams, if enabled.

It can be deployed wherever the wireless exchange of data packets among two or more parties is required. A serial interface (UART), whose data rate and format can be adjusted flexibly, is available for communicating with the host system.

1.2. Block diagram

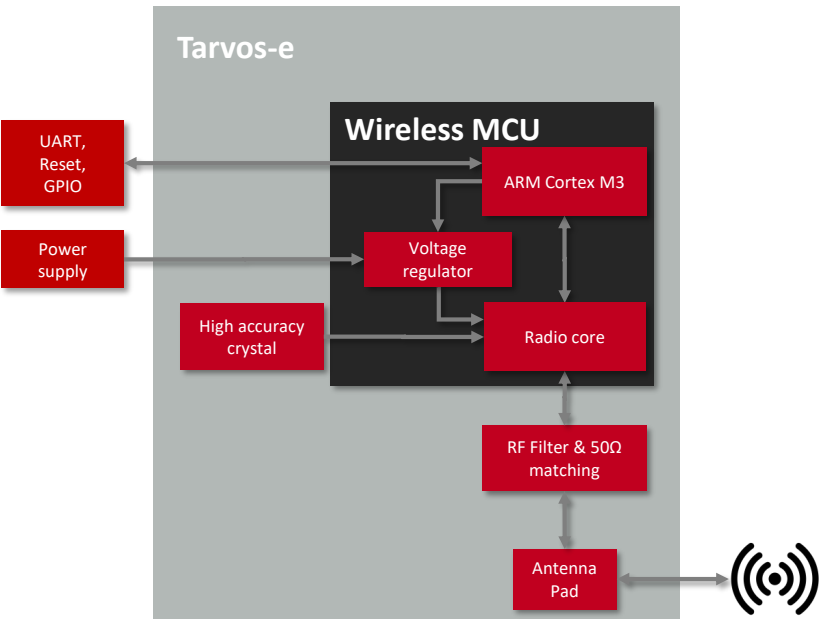


Figure 2: Block diagram

1.3. Ordering information

WE order code	Description
2609051181000	Radio module 868 MHz with antenna pad, Tape & Reel
2609059281001	Evaluation Kit for Tarvos-e radio module, 868 MHz, external antenna

Table 1: Ordering information

2. Electrical specifications

If not otherwise stated, the following parameters have been measured on the EV-Board Tarvos-e-EV with $T = 25\text{ °C}$, $VDD = 3.0\text{ V}$, internal DC-DC converter active and a $50\text{ }\Omega$ connection. Any radio transmission in the standard firmware uses boost mode, independent of the chosen output power.

2.1. Operating conditions

Description	Min.	Typ.	Max.	Unit
Ambient temperature	-40	25	85	°C
Supply voltage (VDD)	2.2 ¹	3.0	3.7	V
Rising supply voltage slew rate	0		100	mV/ μ s
Falling supply voltage slew rate	0		20	mV/ μ s
Falling supply voltage slew rate, with low power flash settings			3	mV/ μ s

Table 2: Operating conditions

2.2. Absolute maximum ratings

Description	Min.	Typ.	Max.	Unit
Supply voltage (VDD)	-0.3		4.1	V
Voltage on any digital pin	-0.3		VDD + 0.3, max 4.1	V
Input RF level			10	dBm
Output RF level, with boost mode		14		dBm

Table 3: Absolute maximum ratings

¹Below 2.2 V, the chipset stops working immediately. A certain buffer for voltage drops should be considered, e.g. when supplying with 2.4 V.

2.3. Power consumption



As a DC/DC voltage regulator is integrated, the current consumption is strongly depending on the supplied voltage level.



The transmit and receive currents are depending on the impedance matching and therefore may vary depending on antenna selection and matching.



The indicated values are the complete current consumption for radio and active MCU. Not to be confused with only radio or only CPU core currents, as sometimes stated by others.



A stable power supply is indispensable to ensure valid operating conditions for the module.

2.3.1. Static

Current consumption is the sum of the CPU current and radio TX or RX current in active modes. Measurements on Tarvos-e-EV with $T = 25\text{ °C}$, $V_{DD} = 3.0\text{ V}$, internal DC-DC converter active and a $50\text{ }\Omega$ connection, unless specified otherwise.

Description	Typ.	Unit
TX current 10 dBm output power, boost mode	20	mA
TX current 14 dBm output power, boost mode	28	mA
RX current	8	mA
Low power (standby) radio off, UART off, RTC running, full RAM retention	1.6	μA
Low power (shutdown) radio off, UART off, RTC off, no RAM retention	0.2	μA

Table 4: Power consumption @3.6 V



As a DC/DC voltage regulator is integrated, the current consumption strongly depends on the supplied voltage level.

Supply Voltage	Current Consumption
3.8 V	26 mA
3.6 V	28 mA
2.2 V	44 mA

Table 5: Power consumption TX 14 dBm at different supply voltages



The transmit and receive currents depend on the impedance matching. Especially the transmit current varies depending on antenna selection and matching.

Load Impedance	Current Consumption
Open	38 mA
50 Ω	28 mA
0 Ω	18 mA

Table 6: Power consumption TX 14 dBm, 3.6 V at loads with different impedances



The indicated values are the complete current consumption for radio and active MCU. Not to be confused with only radio or only CPU core currents, as sometimes stated by others.



A stable power supply is indispensable to ensure valid operating conditions for the module.

2.4. Radio characteristics

Description	Min.	Typ.	Max.	Unit
Frequency band	863.0	868.6	870.0	MHz
Radio data rate	2.5	38.4	400	kbit/s
RX sensitivity				
profile 0		-107		dBm
profile 2		-104		
profile 4		-117		
profile 5		-96		
TX power	0	14	14	dBm

Table 7: Radio characteristics

2.5. Pin characteristics

Property	typ. Value	Unit
Default GPIO maximum current	2	mA
Maximum current of <i>RX_IND</i> , <i>TX_IND</i>	4	mA
Pull up current VDD=1.8 V	71.7	μA
Pull down current VDD=1.8 V ²	21.1	μA
Pull up current VDD=3.8 V	277	μA
Pull down current VDD=3.8 V	113	μA
VIH, Lowest GPIO input voltage reliably interpreted as a HIGH	0.8 * VDD	V
VIL, Highest GPIO input voltage reliably interpreted as a LOW	0.2 * VDD	V

Table 8: Pin characteristics

²The module overall is not specified for 1.8 V, as the radio output amplifier needs minimum 2.2 V. Nevertheless, the GPIOs are specified from Texas Instruments with this value.

3. Pinout

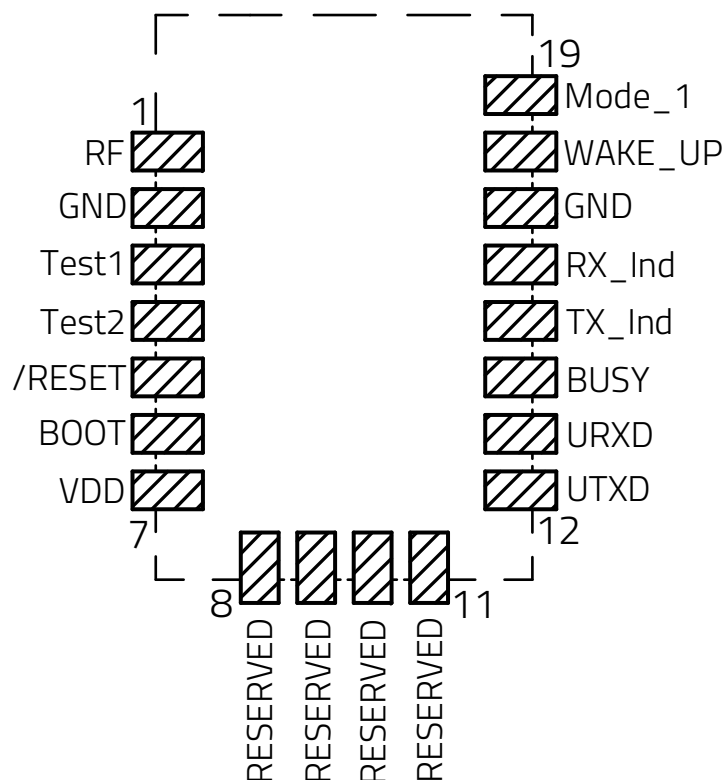


Figure 3: Pinout (top view)

No	Designation	I/O	Description
1	<i>RF</i>	I/O	50 Ω radio connection to transceiver.
2, 17	<i>GND</i>	Supply	Negative supply voltage.
3	<i>Test1</i>	I/O	Testpin, DO NOT CONNECT.
4	<i>Test2</i>	I/O	Testpin, DO NOT CONNECT.
5	<i>/RESET</i>	Input	Apply a rising edge to reset the module (see chapter 9.1.1). Pin has internal pull-up of 100k Ω . Low level holds module in reset state.
6	<i>BOOT</i>	Input	Connect HIGH level or leave open to use application firmware. Connect LOW level to enable the UART bootloader for firmware updates. It uses internal pull up during start up sequence.
7	<i>VDD</i>	Supply	Positive supply voltage.
8	<i>RESERVED</i>	GPIO	Reserved for future use. Do not connect. Internally connected to DIO_7.
9	<i>RESERVED</i>	GPIO	Reserved for future use. Do not connect. Internally connected to DIO_5.
10	<i>RESERVED</i>	GPIO	Reserved for future use. Do not connect. Internally connected to X32k_Q2.
11	<i>RESERVED</i>	GPIO	Reserved for future use. Do not connect. Internally connected to X32k_Q1.
12	<i>UTXD</i>	Output	UART transmission, bootloader TX.
13	<i>URXD</i>	Input	UART reception, bootloader RX. Internal pull-up.
14	<i>BUSY</i>	Output	A HIGH level indicates busy module. A LOW level indicates module idle.
15	<i>TX_IND</i>	Output	Indicates RF data transmission, active = high. Do not connect if not needed.
16	<i>RX_IND</i>	Output	Indicates RF data reception, active = high. Do not connect if not needed.
18	<i>WAKE_UP</i>	Input	Apply a falling edge to wake-up from shutdown or standby mode. Uses an internal pull-down.
19	<i>MODE_1</i>	GPIO	Starts in OpMode (default: command mode) when left unconnected. Apply LOW level during boot to start-up in command mode. Apply HIGH level during boot to start-up in transparent mode. The respective level shall also be steadily applied during normal module operation to prevent leakage current.

Table 9: Pinout

4. Quickstart

4.1. Minimal pin configuration

In factory state, the module is immediately ready for operation in command mode. The following pins are required in the minimal configuration:

/RESET, *BOOT*, *VCC*, *GND*, *BUSY*, *UTXD*, *URXD* and *RF*.

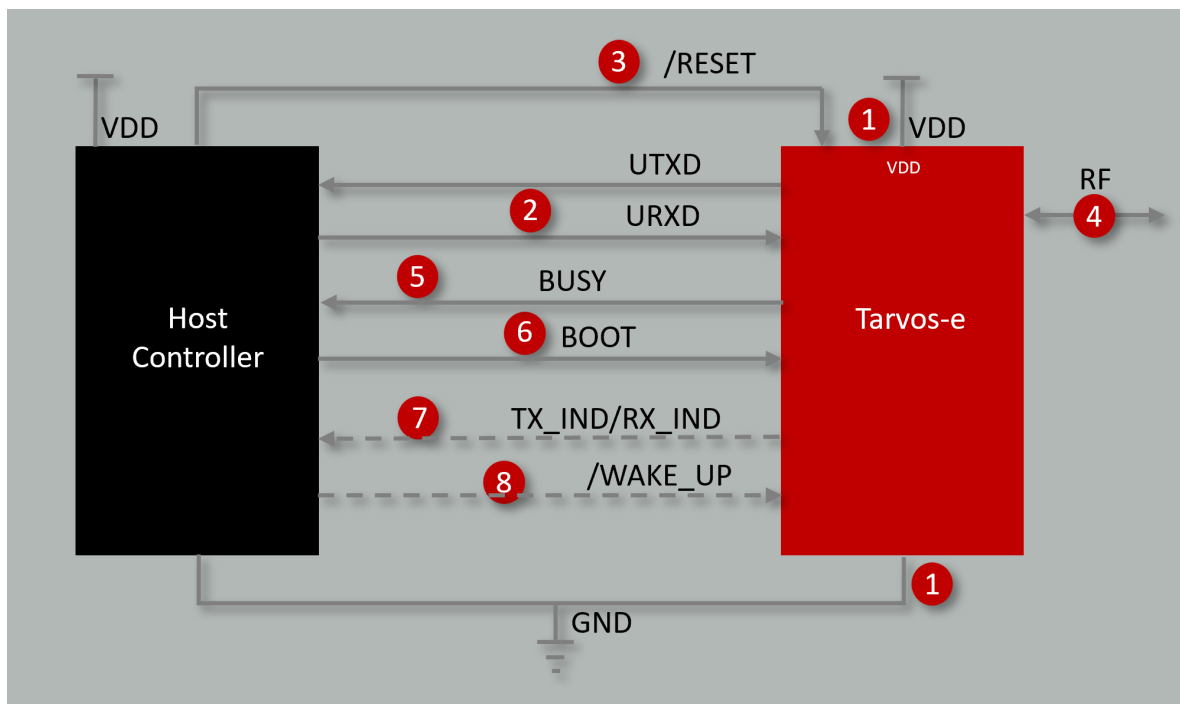


Figure 4: Minimal pin connections

1. Supply voltage and ground
Connect pins *VDD* and *GND* to supply the radio module with power.
2. UART serial interface
Connect the UART pins *UTXD* and *URXD* to the host to control the module via host. No flow control needed.
3. Reset
Connect the */RESET* pin to the host to allow a hard reset of the module.
4. Antenna connection
An antenna must be connected to *RF*.
5. Busy
Connect the *BUSY* pin to the host to allow easy indication of the module.
6. Boot
Connect the *Boot* pin to the host to set the module into bootloader mode to perform firmware updates.

7. (Optional) Wake up

Connect the *WAKE_UP* pin to the host to wake up the module when it is in shutdown or standby mode.

8. (Optional) Radio indication

Connect the *TX_IND* and *RX_IND* pin to the host controller to allow easy indication of RF data transmission/reception.

If the module is connected to a PC or non 3.3 V logic level, a converter cable/IC (e.g. 3.3 V TTL to USB) is necessary to achieve interface compatibility. The Tarvos-e Evaluation Kit already implements such a USB converter to be connected to a PC. Not interpreting the *BUSY* line of the module as described in this manual, may cause undefined behavior and data loss. During the start up sequence, the voltage level on *BOOT* pin is checked. To start the application firmware, the level must be HIGH. An internal pull-up resistor is switched inside the chip during the start up sequence, to do so. To perform a firmware update it is necessary to start the module in it's boot mode by connecting a LOW level externally. In case a pull down resistor is used to get into boot mode the value must be chosen accordingly, as it works against the chip internal pull up, see chapter *Pin characteristics* for details. As example, on the evaluation board a 1000 Ω with a supply voltage of 3.3V is used. After the start up sequence finishes, the *BOOT* pin switches to high impedance to avoid current consumption.

When integrating the Tarvos-e inside an end application it is highly recommended to implement the possibility to update the firmware, through switching *BOOT* pin to LOW level. Refer to chapter *Firmware updates* for more details.

4.2. Power up

Recommended procedure for starting the module into normal operation:

Set and hold the *BOOT* to HIGH and the */RESET* pin to LOW.

After supply voltage is applied to the module and has stabilized, the */RESET* pin shall be tied to LOW level for another Δt of at least 1 ms, to ensure a safe start-up when releasing or applying HIGH to the */RESET* pin.

The module will send a *CMD_RESET_IND* UART message as well as pulling the *BUSY* line to LOW once it has booted and started the application.

Then the *BOOT* pin may be either released or kept at HIGH level.

If the module is used on a battery-powered system, using a matching reset-IC (or a discrete RC block for a delay) is highly recommended to ensure a correct power up and stable behavior towards a battery getting empty. Optional: For activating the transparent mode, the *MODE_1* pin has to be connected and held HIGH before the */RESET* pin is HIGH.

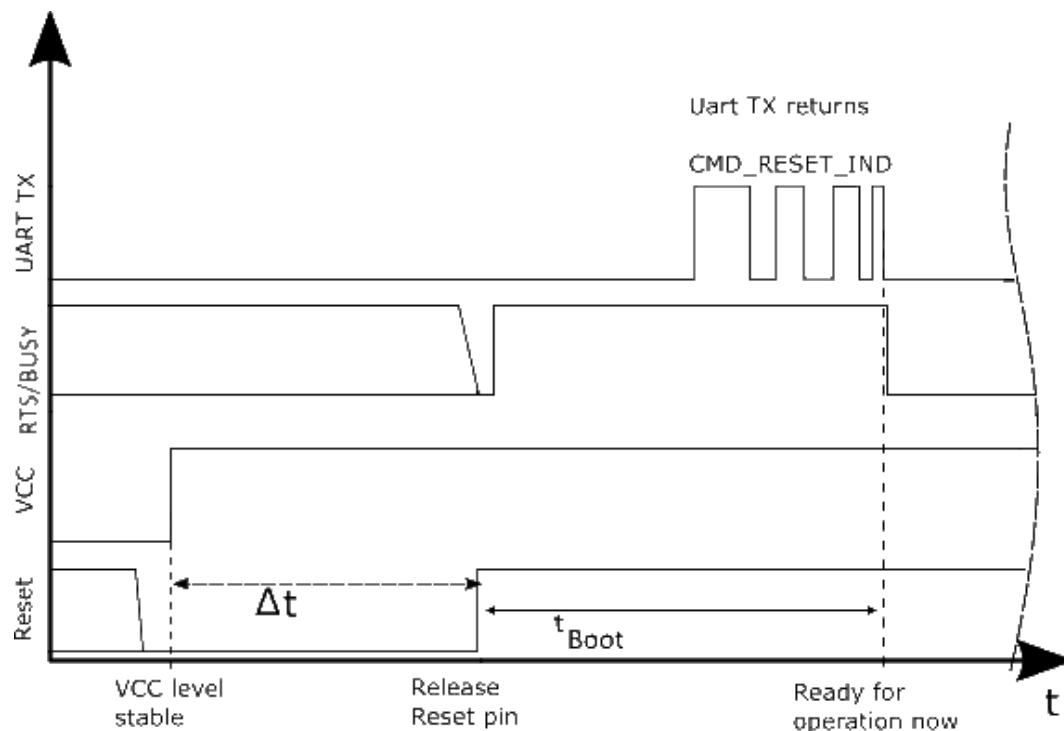


Figure 5: Power up

4.3. Quickstart example

Sending and receiving: Hello World

Connect the two devices (modules, EV-Boards or USB dongles) to a PC. You may need to install FTDI VCP drivers manually (see *FTDI*) or using Windows update. A minimum distance of 2 meters between the two devices should be kept at all times, in order to avoid over-modulation of the receiver.

A terminal program, for example *hterm*, is used to perform the communication via COM ports. The two corresponding COM ports have to be selected and opened with a default configuration of 115200 Baud, 8 data bits, 1 stop bit and parity set to none (8n1).

Baud	115200	Data	8	Stop	1	Parity	None
------	--------	------	---	------	---	--------	------

It needs to be assured that the received data is shown also in hex format, by enabling the corresponding checkbox:

☒ Ascii	☒ Hex
---	---

As soon as the module is ready for operation (at start-up or after a reset), it sends a `CMD_RESET_IND` message on the UART. It may be necessary to push the reset button (or perform `CMD_RESET_REQ`) to trigger a reset and see this message.

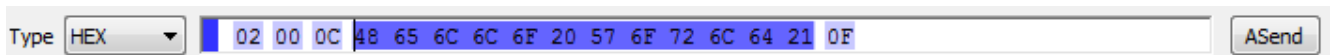
Next, the command interface can be used to configure the module or to transmit data. The

MAC_DefaultAddressMode is 0, which means that all radio frames are broadcasts that can be received by any other compatible radio device with default settings.

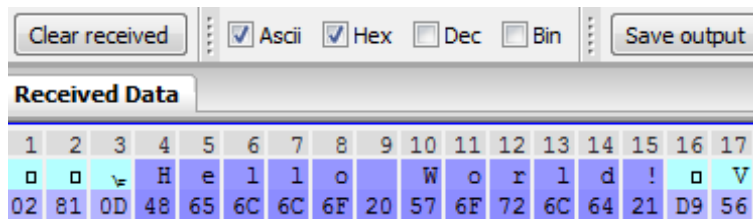
To send the string "Hello World", the corresponding CMD_DATA_REQ has to be inserted into the input line of hterm. The "Type" needs to be changed from "ASC" to "HEX" before entering the first byte. The command CMD_DATA_REQ has the following structure:

Start signal	Command	Length	Payload	CS
0x02	0x00	1 byte	Length Bytes	1 byte

In this example, the payload 0x48 0x65 0x6C 0x6C 0x6F 0x20 0x57 0x6F 0x72 0x6C 0x64 0x21 (Hello World!) has a length of 12 (0x0C) Bytes. The checksum CS is an XOR combination of all previous bytes, which is 0x0F in this case.



Using the "ASend" button followed by pushing the "Start" button, sends the data once. The second module receiving this packet, outputs a CMD_DATAEX_IND message containing the transmitted payload data and the corresponding RSSI value.



In the default address mode (MAC_DefaultAddressMode = 0), the format of the CMD_DATAEX_IND is as follows:

Start signal	Command	Length	Payload	RSSI	CS
0x02	0x81	1 byte	(Length-1) Bytes	1 byte	1 byte

Thus, the CMD_DATAEX_IND message informs us that we received a packet with payload of 13 (0x0D) Bytes. 12 of these Bytes are the transmitted user payload 0x48 0x65 0x6C 0x6C 0x6F 0x20 0x57 0x6F 0x72 0x6C 0x64 0x21 (Hello World!) and one byte is the RSSI value, here 0xD9 (-39dBm in two's complement notation).

5. Functional description

The Tarvos-e can be configured to operate in several modes at the physical, MAC, as well as the network layer. This chapter describes all the available modes of operation.

5.1. Operating modes

The Tarvos-e can be used in the following operating modes:

1. Transparent mode (transparent data transmission) or
2. Command mode (module configuration and data transmission, using the predefined command interface).

The operating mode after power-up can be configured by means of the `OpMode` parameter and the level of the `MODE_1`. By default, the module operates in command mode. Starting in command mode, the module responds with a `CMD_RESET_IND` telegram.



We highly recommend to only use command mode. The *Wireless Connectivity SDK* provides all the commands needed for Tarvos-e as C source code.

5.1.1. Determine operating mode on start-up

During the start-up routine, the module checks the level of the `MODE_1` pin. If a LOW level is detected, the module starts in command mode. If a HIGH level is detected, the module starts in transparent mode. In case of a floating `MODE_1` pin, the `OpMode` parameter is used (default: command mode).



The level of the `MODE_1` pin has a higher priority than the user setting `OpMode`.

<code>MODE_1</code> pin	Operating mode
LOW level detected	Command mode
HIGH level detected	Transparent mode
Floating detected	As defined in <code>OpMode</code>

Table 10: Operating mode at start-up

5.1.2. Switching from transparent to command mode

The command mode can be entered by transmitting the escape sequence "+++" (= 0x2B 0x2B 0x2B) via UART during runtime. The escape sequence has to be the only data in the UART RX buffer. In case of an ongoing radio transmission, the operating mode will be switched once the transmission is finished.

The recommended procedure is:

1. Wait at least 4 byte durations since last transmission to module,
2. Send the escape sequence 0x2B2B2B,
3. Wait until a `CMD_SET_MODE_CNF` is sent by the module.

The successful switchover is acknowledged by a `CMD_SET_MODE_CNF` telegram indicating command mode.

5.1.3. Switching from command to transparent mode

The transparent mode can be entered by using the command `CMD_SET_MODE_REQ` during runtime. In case of an ongoing radio transmission, the operating mode will be switched once the transmission is finished.

The successful switchover is acknowledged by a `CMD_SET_MODE_CNF` telegram indicating transparent mode.

5.1.4. Transparent mode



Applications should not use the data 0x2b2b2b anywhere in the data stream of transparent payload data. This 3 byte sequence is reserved for switching to command mode.

In this mode, data is received via the serial interface and initially buffered. As soon as a specific condition is met, the RF telegram is generated with a preamble, checksum and address information.

Radio transmission in transparent mode behaves the same as `CMD_DATA_REQ` in command mode and uses the configured address information of the corresponding user settings.

The transparent mode does not inform the host if and how many data was sent.



The host shall cause the configured start condition before the maximum number of Bytes is reached in the RX buffer of the UART. In addition the transparent mode shall not be used when repeater mode is enabled.

To initiate an RF transmission, several options are available, as listed in table 11.

Start condition	Description	Dependent user settings
Timeout	Transmission starts if no new character is detected within a configurable period of time after receiving a character via UART. The timeout is reset every time a new character is received.	OpMode_Flags, UART_Timeout
End-of-text-character	Transmission begins when the preconfigured characters are transmitted via UART. End-Of-Text-Character can be one or two Bytes long.	OpMode_Flags, UART_ETX_ Character0, UART_ETX_ Character1
Maximum packet size	Transmission starts when the maximum number of Bytes is reached in the RX buffer of the UART. The maximum number of Bytes depends on the selected RADIO_DefaultRfProfile. This condition is always active and can not be disabled.	RADIO_ DefaultRfProfile

Table 11: Communication in transparent mode

The OpMode_Flags parameter (see chapter 8.2.12) can be used to determine which of the listed combinations is to be used.

5.1.5. BUSY signal, module busy

To prevent misunderstandings the */RTS* signal was renamed to *BUSY* (in comparison to the Tarvos-III radio module). It still signalizes a busy status of the internal buffers of the module, which means, when *BUSY* is set HIGH, all incoming UART Bytes may be discarded by the module. *BUSY* is set when any of the events in the prior chapter has occurred.

In command mode due to nature of the commands and replies being effectively a flow control by the protocol itself, the situation of the radio module being busy is much more relaxed than compared to transparent mode. The SDK for instance is not implementing *BUSY* and still works without issues in the provided examples. But that may not be true for each and every application on the host side that maximizes stress on the buffers inside the radio module.

Depending on the application and network it may be necessary to implement a guard interval of at least 5ms plus 4 UART byte durations when the busy signaling happened while the host was transmitting data to the radio module, to ensure a safe state of the UART receive buffer content in the Tarvos-e especially when in transparent mode.



The *BUSY* pin handling shall be implemented into the host, in order to prevent data loss in transparent mode.

5.1.6. Command mode

This operating mode primarily serves module configuration. The module acts as a slave and can be fully controlled by an external host using the commands of the command interface (see chapter 7).

It can also be used for wireless transmission of payload data, providing a feedback dependent on the transmission success.

5.2. Physical layer

At the physical layer, the Tarvos-e can be configured to use one of the following radio profiles (see parameter `RADIO_DefaultRfProfile`).

Radio profile 4 is optimized to provide long range transmission with small payloads, whereas profile 5 enables a higher data rate and payload size.



The radio profile 3 is not available in Tarvos-e (in comparison to the Tarvos-III radio module).

Radio profile	Data rate (gross) [kcps]	Modulation	Max packet size [byte]
0	38.4	FSK	128
2	100	FSK	128
4 (long range mode)	20 (=2.5 kbps net)	FSK (with FEC)	64
5	400	GFSK	224

Additionally, the frequency channel of operation is configurable to avoid interference between several subnets of radio devices (see `RADIO_DefaultRfChannel`). The radio parameters need to be chosen for optimal performance based on the required range, data rate and maximum payload size, keeping in mind the compliance with valid regulatory requirements. A detailed description for configuring these parameters can be found in chapter 7 and chapter 8.

5.3. MAC and network layer

5.3.1. Addressing modes

In order to interconnect several modules and build a network or to send data to specific devices, the Tarvos-e supports addressing at MAC and network levels. Based on the address mode of the module configured using the user setting `MAC_DefaultAddressMode`, each device can be configured with an address (1 or 2 byte) and a network ID (1 byte) that is defined by the user settings `MAC_SourceAddr` and `MAC_SourceNetID`, respectively.

Address mode	MAC address size [byte]	Network address size [byte]
0	0	0
1	1	0
2	1	1
3	2	1

Depending on the selected address mode, up to 254 network IDs and up to 65,534 addresses are supported. 0xFF and 0xFFFF are used as broadcast addresses.



Note that the RF settings (e.g. RF profile, RF channel, address mode, repeater settings) must be the same for all nodes in the network. Violation may cause interrupted transmission or received packets that cannot be interpreted correctly. In addition, the timing parameters, in case of repeater or enabled ACKs, must be the same for all nodes in a network. Radio messages of devices that are using the same radio channel may interfere with each other, leading to possible collisions and packet loss.

5.3.2. Unicast

A module can use the command `CMD_DATA_REQ` to send data to a pre-defined destination, specified by the parameters `MAC_DefaultDestAddr` and `MAC_DefaultDestNetID`. Besides this, the command `CMD_DATAEX_REQ` triggers the data transmission to the address specified in the command.

5.3.3. Multicast/Broadcast

The destination address or destination network ID of 0xFF (255) or 0xFFFF (65535), stands for a broadcast, which will trigger any compatible receiver to interpret this frame to forward it to its host.

5.3.4. Acknowledgement and retries

In order to improve reliability in communication, the module can be configured to use the radio ACK and retry mechanism. It can be activated using the parameter `MAC_NumRetrys` accordingly and only in case of non-broadcast messages.

5.3.5. Packet sniffer mode

The address resolution can be disabled ("packet sniffer") by enabling the sniffer mode in the user setting `CfgFlags`. A module in sniffer mode will accept all data packets (ignoring the target address) and forward them to the serial interface. Furthermore, it does not send any ACK and cannot work as repeater at the same time (see section 13).

5.3.6. Repeater mode and mesh network

The module can be run as a repeater to artificially extend the range of sending devices in an existing network. A module configured as repeater, simply re-transmits the received packet after a random back-off time. This mode allows options to build a "flooding mesh" network, described in detail in chapter 13.



it's not intended and not recommended to just enable the repeater mode on any module that is part of the network.

5.4. System configuration parameters

The parameters that determine the functionality of the module, are classified into two categories. The non-volatile user settings (see chapter 8) values that can be modified using the `CMD_SET_REQ` command retain their values after a power reset.



Note that each `CMD_SET_REQ` will consume one flash erase/write cycle, which is limited due to the hardware (100,000 cycles guaranteed, see TI CC1310 datasheet).

On the other hand, the volatile settings (called "Runtime settings") can be accessed by explicit commands (see chapter 7.4) and used to quickly (but temporarily) modify specific parameters without using flash cycles. These settings are only valid until a reset is performed and shall be used when frequent updates of settings are necessary.

6. Host connection

6.1. Serial interface: UART

The configuration in factory state of the UART is 115200 Baud with data format of 8 data bits, no parity and 1 stop bit ("8n1"). The baud rate of the UART can be configured by means of the user setting `UART_Baudrate`. The data format is fixed to 8n1.

The output of characters on the serial interface runs with secondary priority. For this reason, short interruptions may occur between the outputs of individual successive Bytes. The host must not implement too strict timeouts between two Bytes, in order to be able to receive packets that have interruptions in between. At least four full byte durations (32 bits) delay between two successive Bytes shall be accepted by the host.

For the direction "host to module", the host must respect byte-wise the line *BUSY*, which will indicate that the next byte of the packet can be received by the module. This direction also accepts a pause of up to four full byte durations (32 bits) delay between two successive Bytes, before discarding received content (without user notification). To prevent a too early use of the module, an additional delay of $\geq 100\mu\text{s}$ or 4 byte durations, whatever number is bigger, shall be implemented by the host when *BUSY* shows an edge from HIGH to LOW (i.e. module switches from busy to idle).

7. The command interface

7.1. Overview

The module acts as a slave and can be fully controlled by an external host. The configuration as well as the operation of the module can be managed by predefined commands that are sent as telegrams over the UART interface of the module.

The commands of the command interface can be divided into 3 groups:

- **Requests:** The host requests the module to trigger any action, e.g. in case of the request `CMD_RESET_REQ` the host asks the module to perform a reset.
- **Confirmations:** On each request, the module answers with a confirmation message to give a feedback on the requested operation status. In case of a `CMD_RESET_REQ`, the module answers with a `CMD_RESET_CNF` to tell the host whether the reset will be performed or not.
- **Indications and Responses:** The module indicates spontaneously when a special event has occurred. The `CMD_DATAEX_IND` indicates for example that data was received via radio.

Start signal	Command	Length	Payload	CS
0x02	1 Byte	1 Byte	Length Bytes	1 Byte

Start signal 0x02 (1 Byte)

Command One of the predefined commands (1 Byte), the module implements new and modified commands in comparison to other radio compatible modules.

Length Specifies the number of payload data in the following field.

Payload Variable number (defined by the length field) of data or parameters.

Checksum Byte wise XOR combination of all preceding Bytes including the start signal, i.e.
 $0x02 \wedge \text{Command} \wedge \text{Length} \wedge \text{Payload} = \text{CS}$



Host integration example codes for checksum calculation and command frame structure can be found in annex A and B, as well as in the *Wireless Connectivity SDK*.

All commands of type request must obey the following rules:

- Only one request at a time may be active. Wait for confirmation of the previous request and implement a suiting timeout (depends on the command or action that was requested, 500 ms should cover the worst-case time).
- Indications are spontaneous messages, they may occur in between a command request and its confirmation.

- A high *BUSY* line signalizes that the module UART is not ready for reception. Thus, any Byte(s) sent from the host will be discarded by the module without further user notification ("module busy"). If "module busy" occurs while sending a command to the module, it is necessary to resend this entire command again after *BUSY* pin status shows "module idle" again.

7.2. Data transfer and reception in the command mode

This group of commands include the commands that either are used to request a radio telegram to be sent or indicates a received frame.

7.2.1. CMD_DATA_REQ

This command serves the simple data transfer in the command mode. Transmission takes place on the configured channel to the previously parametrised destination address (taken from the volatile runtime settings). This command is especially suitable for transmission for a point-to-point connection. The maximum number of payload data Bytes depends on the chosen RADIO_DefaultRfProfile.

Format:

Start signal	Command	Length	Payload	CS
0x02	0x00	1 Byte	Length Bytes	1 Byte

Response (CMD_DATA_CNF):

Start signal	Command 0x40	Length	Status	CS
0x02	0x40	0x01	1 Byte	1 Byte

Status:

0x00: ACK received or not requested (MAC_NumRetrys is 0, MAC_DefaultAddressMode is 0 or a broadcast address is set as destination address)

0x01: No ACK received within a time-out after using all MAC_NumRetrys

0x03: Radio channel is busy (LBT)

0x04: Module is currently busy

0xFF: Invalid (payload too long)

7.2.2. CMD_DATAEX_REQ

This command serves data transfer in a network with several parties. Both the RF channel to use and the destination address (depending on the parametrised address mode) are specified along with the command. The maximum number of payload data Bytes depends on the chosen RADIO_DefaultRfProfile. The entered channel, destination network and destination address are loaded into the volatile runtime settings and thus are kept until the system is reset or these values are modified again.



Please note that the format of this command depends on the configured MAC_DefaultAddressMode.

Address mode 0:

Start signal	Command	Length	Channel	Payload	CS
0x02	0x01	Payload len. + 1	1 Byte	Payload len. Bytes	1 Byte

Address mode 1:

Start signal	Command	Length	Channel	Dest. address	Payload	CS
0x02	0x01	Payload len. + 2	1 Byte	1 Byte	Payload len. Bytes	1 Byte

Address mode 2:

Start signal	Command	Length	Channel	Dest. netID	Dest. address	Payload	CS
0x02	0x01	Payload len. + 3	1 Byte	1 Byte	1 Byte	Payload len. Bytes	1 Byte

Address mode 3:

Start signal	Command	Length	Channel	Dest. netID	Dest. address	Payload	CS
0x02	0x01	Payload len. + 4	1 Byte	1 Byte	2 Byte (LSB first)	Payload len. Bytes	1 Byte

Response:

Start signal	CMD_DATA_REQ 0x40	Length	Status	CS
0x02	0x40	0x01	1 Byte	1 Byte

Status:

0x00: ACK received or not requested (MAC_NumRetrys is 0, MAC_DefaultAddressMode is 0 or a broadcast address is set as destination address)

0x01: No ACK received within a time-out after using all MAC_NumRetrys

0x02: Invalid channel selected

0x03: Radio channel is busy (LBT)

0x04: Module is currently busy

0xFF: Invalid (payload too long)

7.2.3. CMD_DATAEX_IND

This telegram indicates the reception of data Bytes and represents the counterpart to the commands CMD_DATA_REQ and CMD_DATAEX_REQ. Apart from the RX field strength (RSSI value given in two's complement notation), this telegram also displays the source address of the sending device (depending on the parametrised address mode).



Please note that the format of this command depends on the configured MAC_DefaultAddressMode.

Format in address mode 0:

Start signal	Command	Length	Payload	Field strength	CS
0x02	0x81	Payload len. + 1	Payload len. Bytes	1 Byte	1 Byte

Format in address mode 1:

Start signal	Command	Length	Sender address	Payload	Field strength	CS
0x02	0x81	Payload len. + 2	1 Byte	Payload len. Bytes	1 Byte	1 Byte

Format in address mode 2:

Start signal	Command	Length	Sender network id	Sender address	Payload	Field strength	CS
0x02	0x81	Payload len. + 3	1 Byte	1 Byte	Payload len. Bytes	1 Byte	1 Byte

Format in address mode 3:

Start signal	Command	Length	Sender network id	Sender address	Payload	Field strength	CS
0x02	0x81	Payload len. + 4	1 Byte	2 Byte (LSB first)	Payload len. Bytes	1 Byte	1 Byte

7.2.4. CMD_REPEAT_IND

This command indicates that the module has repeated a data packet when acting in repeater mode. The source address and network id is the address of the origin sender of the RF packet, the destination address and network id is the address of the device that is supposed to receive the RF packet.

Format in address mode 0:

Start signal	Command	Length	Status	Address mode	CS
0x02	0x80	0x02	1 Byte	0x00	1 Byte

Format in address mode 1:

Start signal	Command	Length	Status	Address mode	Dest. address	Source address	CS
0x02	0x80	0x04	1 Byte	0x01	1 Byte	1 Byte	1 Byte

Format in address mode 2:

Start signal	Com.	Length	Status	Address. mode	Dest. NetID	Dest. address	Source NetID	Source address	CS
0x02	0x80	0x06	1 Byte	0x02	1 Byte	1 Byte	1 Byte	1 Byte	1 Byte

Format in address mode 3:

Start signal	Com.	Length	Status	Address. mode	Dest. NetID	Dest. address	Source NetID	Source address	CS
0x02	0x80	0x08	1 Byte	0x03	1 Byte	2 Byte (LSB first)	1 Byte	2 Byte (LSB first)	1 Byte

Status:

0x00: OK

0x01: Failed

0x03: Radio channel is busy (LBT)

0x04: Module is currently busy

7.2.5. CMD_DUTYCYCLE_IND

This message indicates that the module has performed one or multiple radio sending actions (i.e. normal data tx, repeating of data and acknowledgements). The message contains the transmission time since the last CMD_DUTYCYCLE_IND message or the last module restart message (CMD_RESET_IND) in 1 μ s resolution. The 32 bit unsigned integer value is transmitted in LSB first notation. This information can be used to track the duty cycle.

Start signal	Command	Length	Time	CS
0x02	0x90	0x04	4 Bytes	1 Byte



This message has to be enabled using the user setting CfgFlags, by setting Bit1 to '1' (OR operation with 0x0002).

7.2.5.1. Example

One or more Radio packets have been transmitted using a time of 0x00006C95 (27797_{dec}) μ s.

Start signal	Command	Length	Time	CS
0x02	0x90	0x04	0x95 0x6C 0x00 0x00	0x6F

7.3. Requesting parameters, actions and events

This group includes all commands that will return read-only parameters or request actions in the module.

7.3.1. CMD_RESET_REQ

This command triggers a software reset of the module. The reset is performed after the acknowledgement is transmitted. All volatile settings are initialized with their defaults.

Format:

Start signal	Command	Length	CS
0x02	0x05	0x00	0x07

Response (CMD_RESET_CNF):

Start signal	Command 0x40	Length	Status	CS
0x02	0x45	0x01	1 Byte	1 Byte

Status:

0x00: Request successfully received and processed

0x01: Request not successful

As soon as the module has restarted a CMD_RESET_IND is printed on the UART and the *BUSY* line will show "module idle".

7.3.2. CMD_RESET_IND

This message indicates that the module has restarted. After the *BUSY* line is low and the start-up time-out has passed, the module is ready to receive UART data and radio frames.

Start signal	Command	Length	Mode	CS
0x02	0x85	0x01	0x10	0x96

7.3.3. CMD_SHUTDOWN_REQ

This command triggers the shut down mode of the chip, which is the mode with lowest power consumption. The shut down is performed after the command confirmation message is transmitted. The UART interface is disabled in shut down mode.

Format:

Start signal	Command	Length	CS
0x02	0x0E	0x00	0x0C

Response (CMD_SHUTDOWN_CNF):

Start signal	Command 0x40	Length	Status	CS
0x02	0x4E	0x01	1 Byte	1 Byte

Status:

0x00: Request successfully received and processed

0x01: Request not successful

To wake-up from shut down mode, a falling edge has to be applied to the *WAKE-UP* pin. In this case, the module restarts such that all volatile settings are lost. As soon as it has restarted a *CMD_RESET_IND* message is printed on the UART. Please note that in shut down mode, the *WAKE-UP* pin has an internal pull-down to ensure the wake-up is not performed accidentally due to a floating pin.

7.3.4. CMD_STANDBY_REQ

This command triggers the standby mode of the chip, a low power mode with RAM retention. The standby mode is entered after the command confirmation message is transmitted. The UART interface is disabled in standby mode. The latency is smaller than the latency caused by a complete restart of the module as done in the shut down mode.

Format:

Start signal	Command	Length	CS
0x02	0x0F	0x00	0x0D

Response (CMD_STANDBY_CNF):

Start signal	Command 0x40	Length	Status	CS
0x02	0x4F	0x01	1 Byte	1 Byte

Status:

0x00: Request successfully received and processed

0x01: Request not successful

To wake-up from standby mode, a falling edge has to be applied to the *WAKE-UP* pin. Please note that in standby mode, the *WAKE-UP* pin has an internal pull-down to ensure the wake-up is not performed accidentally due to a floating pin. When a falling edge is detected, the module wakes up but does not revert to factory settings as the RAM content is retained and all volatile settings are kept. Upon being idle again, a *CMD_STANDBY_IND* message is printed on the UART and the *BUSY* pin will show a low level.

7.3.5. CMD_STANDBY_IND

This message indicates that the module woke up from standby mode and is ready for operation.

Start signal	Command 0x80	Length	Status	CS
0x02	0x8F	0x01	0x00	0x8C

Status:

0x00: wake-up successful

7.3.6. CMD_RSSI_REQ

This command returns the RX level of the last received packet determined by the transceiver IC in the form of a signed two's complement. The current RSSI value of the radio IC ("live RSSI value") cannot be requested by means of this command.



This function cannot be used to determine the live noise value on the radio channel.

Format:

Start signal	Command	Length	CS
0x02	0x0D	0x00	0x0F

Response (CMD_RSSI_CNF):

Start signal	Command 0x40	Length	RX level	CS
0x02	0x4D	0x01	1 Byte	1 Byte

The value obtained in this way delivers the RX level $RSSI_{dBm}$ in dBm as follows.

Example: Conversion of the hexadecimal value in two's complement notation to a decimal $RSSI_{dec}$

$$0xBD_{hex} = 10111101_{bin} \Rightarrow -128 + 0 \times 64 + 1 \times 32 + 1 \times 16 + 1 \times 8 + 1 \times 4 + 0 \times 2 + 1 \times 1 = -67dBm$$



If the RSSI equals 0x80 (-128dBm), there is no RSSI value available yet.

7.4. Modification of volatile parameters

This group contains all functions that will modify runtime settings while the module is running. These settings are volatile and will be reset to their defaults (see chapter 8) on a reset of the module or when waking up after a shut down command.

7.4.1. CMD_SET_PAPOWER_REQ

This command is used to set the radio TX-power. Unlike the user settings parameter `RADIO_DefaultRfTXPower`, this is a volatile runtime parameter, but its power value is used in the same way. Thus, see section 8.2.3 for more information.



The parameters must be chosen carefully to reach good functionality and compliance with valid national regulatory requirements. The user of this module is solely responsible that the end device in which this product is designed in, adheres to all national applicable statutory regulations.

The power value is entered in the complement on two format.

Format:

Start signal	Command	Length	Power	CS
0x02	0x11	0x01	1 Byte	1 Byte

Response (CMD_SET_PAPOWER_CNF):

Start signal	Command 0x40	Length	Configured power	CS
0x02	0x51	0x01	1 Byte	1 Byte

7.4.1.1. Example

Setting the power to +14 dBm:

Start signal	Command	Length	Configured power	CS
0x02	0x11	0x01	0x0E	0x1C

Response:

Start signal	Command 0x40	Length	Configured power	CS
0x02	0x51	0x01	0x0E	0x5C

7.4.2. CMD_SET_CHANNEL_REQ

This command is used to select the radio channel. Unlike the user settings parameter `RADIO_DefaultRfChannel`, this is a volatile runtime parameter.



The parameters must be chosen carefully to reach good functionality and compliance with valid national regulatory requirements. The user of this module is solely responsible that the end device in which this product is designed in, adheres to all national applicable statutory regulations.

Format:

Start signal	Command	Length	Channel	CS
0x02	0x06	0x01	1 Byte	1 Byte

Response (CMD_SET_CHANNEL_CNF):

Start signal	Command 0x40	Length	Configured channel	CS
0x02	0x46	0x01	1 Byte	1 Byte

7.4.2.1. Example

Selection of channel 108:

Start signal	Command	Length	channel	CS
0x02	0x06	0x01	0x6C	0x69

Response:

Start signal	Command 0x40	Length	Configured channel	CS
0x02	0x46	0x01	0x6C	0x29

7.4.3. CMD_SET_DESTNETID_REQ

This command serves to configure the Dest. netID in address mode 2 and 3. Unlike the user settings parameter MAC_DefaultDestNetID, this is a volatile runtime parameter.

Format:

Start signal	Command	Length	Dest. netID	CS
0x02	0x07	0x01	1 Byte	1 Byte

Return (CMD_SET_DESTNETID_CNF):

Start signal	Command 0x40	Length	Status	CS
0x02	0x47	0x01	1 Byte	1 Byte

Status:

0x00: Request successfully received and processed

0x01: Request not successful

7.4.4. CMD_SET_DESTADDR_REQ

This command serves to configure the destination address in address modes 1, 2 and 3. Unlike the user settings parameter MAC_DefaultDestAddr, this is a volatile runtime parameter.

Format: Mode 1 + 2:

Start signal	Command	Length	Dest. address	CS
0x02	0x08	0x01 or 0x02	1 Byte or 2 Byte	1 Byte

Response (CMD_SET_DESTADDR_CNF):

Start signal	Command 0x40	Length	Status	CS
0x02	0x48	0x01	1 Byte	1 Byte

Status:

0x00: Request successfully received and processed

0x01: Request not successful

7.4.5. CMD_SET_MODE_REQ

This command triggers a change from command mode to transparent mode. The mode change is performed after the acknowledgement is transmitted.

Format:

Start signal	Command	Length	OpMode	CS
0x02	0x04	0x01	0x00	0x07

Response (CMD_SET_MODE_CNF):

Start signal	Command 0x40	Length	Status	OpMode	CS
0x02	0x44	0x02	1 Byte	1 Byte	1 Byte

Status:

0x00: Request successfully received and processed

0x01: Request not successful

OpMode:

0x00: Transparent mode

0x10: Command mode

7.5. Modification of non-volatile parameters

The non-volatile parameters are also called user settings and are stored in a special flash location. These settings can also be configured using our Windows PC software "ACC".



The ACC software is available under request. For this, contact our technical support team under WCS@we-online.com.

7.5.1. CMD_SET_REQ

This command enables direct manipulation of the parameters in the module's non-volatile user settings. The respective parameters are accessed by means of the corresponding SettingsIndex. Parameters with size of two or more Bytes have to be transferred with the LSB first unless otherwise specified.



The modified parameters only take effect after a restart of the module. This can be done by a CMD_RESET_REQ or using the /RESET pin. After a CMD_SET_REQ was sent to the module and the CMD_SET_CNF was received from the module, the host shall not send any other commands than a CMD_SET_REQ, a CMD_GET_REQ or a CMD_RESET_REQ to the module before it is re-started.



The validity of the specified parameters is not verified by the application. Incorrect values can result in device malfunction up to a scenario where the firmware of the module needs to be re-flashed to get it operating again!



Any use of CMD_SET_REQ will consume one flash erase/write cycle. It's recommended to perform a CMD_GET_REQ on the corresponding parameter first and then decide if a change of the parameter using a CMD_SET_REQ to change the parameter is needed. Flash erase/write cycles are limited through hardware (guaranteed minimum 100k cycles). For frequently changing parameters use the volatile parameters "Runtime settings", see chapter 7.4.



To store the parameters in the flash memory of the module, the particular memory segment must be buffered into RAM, then to be erased entirely and then restored from RAM.

If a reset or VCC instability occurs during this procedure (e.g. due to supply voltage fluctuations), the entire memory area may be destroyed and the module can only be resurrected by means of a JTAG or Bootloader firmware update. Recommended procedure: First verify the configuration of the module with CMD_GET_REQ and only apply a CMD_SET_REQ if required. Make sure the VCC is stable and no reset occurs during this procedure.

Format:

Start signal	Command	Length	SettingsIndex	Parameter	CS
0x02	0x09	1 Byte	1 Byte	(Length - 1) Bytes	1 Byte

Response (CMD_SET_CNF):

Start signal	Command 0x40	Length	Status	CS
0x02	0x49	0x01	1 Byte	1 Byte

Status:

0x00: Request successfully received and processed

0x01: Operation failed due to invalid parameter

7.5.2. CMD_GET_REQ

This command can be used to query the user settings parameters. The respective parameters are accessed by means of the corresponding SettingsIndex.



Parameters with size of two or more Bytes will be transmitted LSB first unless noted otherwise.

Format:

Start signal	Command	Length	SettingsIndex	CS
0x02	0x0A	0x01	1 Byte	1 Byte

Response (CMD_GET_CNF):

Start signal	Command 0x40	Length	Status	Parameter	CS
0x02	0x4A	1 Byte	1 Byte	(Length - 1) Bytes	1 Byte

Status:

0x00: Request successfully received and processed

0x01: Request not successful

7.5.3. CMD_FACTORY_RESET_REQ

This command restores the default user settings of the module. If this was successful, a software reset of the module is performed in addition.

Format:

Start signal	Command	Length	CS
0x02	0x12	0x00	0x10

Response (CMD_FACTORY_RESET_CNF):

Start signal	Command 0x40	Length	Status	CS
0x02	0x52	0x01	1 Byte	1 Byte

Status:

0x00: Request successfully received and processed

0x01: Request not successful

7.6. Message overview

CMD	Message name	Short description	Chapter
0x00	CMD_DATA_REQ	Send data to configured address	7.2.1
0x01	CMD_DATAEX_REQ	Send data to specific address	7.2.2
0x04	CMD_SET_MODE_REQ	Switch operating mode	7.4.5
0x05	CMD_RESET_REQ	Reset module	7.3.1
0x06	CMD_SET_CHANNEL_REQ	Change the RF channel	7.4.2
0x07	CMD_SET_DESTNETID_REQ	Set the destination network id	7.4.3
0x08	CMD_SET_DESTADDR_REQ	Set the destination address	7.4.4
0x09	CMD_SET_REQ	Change the user settings	7.5.1
0x0A	CMD_GET_REQ	Read the user settings	7.5.2
0x0D	CMD_RSSI_REQ	Request RSSI of last packet	7.3.6
0x0E	CMD_SHUTDOWN_REQ	Go to shut down mode	7.3.3
0x0F	CMD_STANDBY_REQ	Go to standby mode	7.3.4
0x11	CMD_SET_PAPOWER_REQ	Change the radio TX power	7.4.1
0x12	CMD_FACTORY_RESET_REQ	Perform a factory reset	7.5.3
0x40	CMD_DATA_CNF	Data has been sent	7.2.1
0x45	CMD_RESET_CNF	Reset request received	7.3.1
0x46	CMD_SET_CHANNEL_CNF	Channel has been updated	7.4.2
0x47	CMD_SET_DESTNETID_CNF	Destination network id has been updated	7.4.3
0x48	CMD_SET_DESTADDR_CNF	Destination address has been updated	7.4.4
0x49	CMD_SET_CNF	User settings have been updated	7.5.1
0x4A	CMD_GET_CNF	Return the requested user setting values	7.5.2
0x4D	CMD_RSSI_CNF	Return the requested RSSI value	7.3.6
0x4E	CMD_SHUTDOWN_CNF	Shut down request received	7.3.3
0x4F	CMD_STANDBY_CNF	Standby request received	7.3.4
0x51	CMD_SET_PAPOWER_CNF	RF TX power has been updated	7.4.1
0x52	CMD_FACTORY_RESET_CNF	Factory reset request received	7.5.3
0x80	CMD_REPEAT_IND	Data has been repeated	7.2.4
0x81	CMD_DATAEX_IND	Data has been received	7.2.3
0x85	CMD_RESET_IND	Reset has been applied	7.3.2
0x8F	CMD_STANDBY_IND	Woke up from standby mode	7.3.5
0x90	CMD_DUTYCYCLE_IND	Radio packet has been transmitted	7.2.5

Table 12: Message overview

8. User settings - Module configuration values

8.1. Difference between volatile and non-volatile settings

The so-called user settings are stored permanently into the internal flash of the module. At start-up, these user settings are loaded as start values into the volatile settings ("Runtime settings"). Some of the runtime settings can be modified by special commands (see chapter 7.4). These runtime settings are lost and replaced by the user settings content when the module is restarted.



See chapters 7.4 and 7.5 for methods to change volatile and/or non-volatile settings.

The non-volatile user settings can be modified by means of specific commands in the configuration mode (CMD_SET_REQ) of the module. These parameters are stored permanently in the module's flash memory. All settings are described on the following pages. After changing those parameters, a reset will be necessary to make use of the new settings.



The validity of the specified parameters given with a CMD_SET_REQ is not verified. Incorrect values can result in device malfunction and may even result in the need of re-flashing the entire module firmware!

8.2. Modifying the user settings

The following chapters will give examples for the modification of many parameters using the commands CMD_SET_REQ and CMD_GET_REQ. The PC software ACC (AMBER Config Center, version 3.4.3 or newer) can also be used to change non-volatile parameters.

8.2.1. UART_Baudrate: Configure the UART speed

Settings index	Designation	Permissible values	Default value	Permissions	Number of Bytes
0	UART_Baudrate	9600 - 921600	115200	read/write	4

The user setting UART_Baudrate is a 32 bit field that contains the symbol rate for the communication interface. The format for the parameter value is LSB first.



After changing the baud rate using the `CMD_SET_REQ`, the module restarts using the new baud rate. Thus, do not forget to update the baud rate of the connected host controller to be able to use the module's UART further on.



Since the UART baud rate is derived from the peripheral lock using a prescaler, errors to the exactly selected baud rate are to be expected. This variation gets worse the higher the selected baud rate is.



Double check the byte-order of the parameter. It is to be used "LSB first". Wrong values may lead to a condition where talking with the module is not possible anymore.

8.2.1.1. Example 1

Set the baud rate of the module to 9600 Baud ($0x00002580_{MSBfirst}$ corresponds to $0x80250000_{LSBfirst}$) using the `CMD_SET_REQ` with Settings index 0:

Start signal	Command	Length	Settings index	Parameter	CS
0x02	0x09	0x05	0x00	0x80 0x25 0x00 0x00	0xAB

Response `CMD_SET_CNF`: Successfully modified the setting.

Start signal	Command 0x40	Length	Status	CS
0x02	0x49	0x01	0x00	0x4A

8.2.1.2. Example 2

Request the baud rate of the module using `CMD_GET_REQ`:

Start signal	Command	Length	Settings index	CS
0x02	0x0A	0x01	0x00	0x09

Response `CMD_GET_CNF`: Successfully read out the baud rate 0x00002580 (9600 Baud).

Start signal	Command 0x40	Length	Status	Parameter	CS
0x02	0x4A	0x05	0x00	0x80 0x25 0x00 0x00	0xE8

8.2.2. RADIO_DefaultRfProfile: Configure the RF-settings

Settings index	Designation	Permissible values	Default value	Permissions	Number of Bytes
1	RADIO_DefaultRfProfile	0, 2, 4, 5	0	read/write	1

The user setting RADIO_DefaultRfProfile is an 8 Bit field that addresses the applied RF configuration.



The parameter must be chosen with prudence to reach good functionality and compliance with valid regulatory requirements as the EN 300 220 in the European Union or the FCC in the United States of America.



After modification of the RADIO_DefaultRfProfile, please check whether the RADIO_DefaultRfChannel has to be updated too.

Radio profile	Data rate (gross) [kcps]	Modulation	Max packet size [byte]	Max packet duration [ms]
0	38.4	FSK	128	40
2	100	FSK	128	20
4 (LRM)	20 (=2.5 kbps net)	FSK (with FEC)	64	300
5	400	GFSK	224	10

Table 13: Radio profiles



Due to the low data rate in radio profile 4 the packet size is reduced. The maximum allowed packet duration is 1000 ms, respective 300 ms. The receiver and sender will not accept larger packets than Max packet size Bytes.



The repeater mode (flooding mesh) is currently only supported in profiles 0, 2 and 5.

8.2.2.1. Example 1

Set the radio profile to 0 using the CMD_SET_REQ:

Start signal	Command	Length	Settings index	Parameter	CS
0x02	0x09	0x02	0x01	0x00	0x08

Response CMD_SET_CNF: Successfully modified the setting.

Start signal	Command 0x40	Length	Status	CS
0x02	0x49	0x01	0x00	0x4A

8.2.2.2. Example 2

Request the radio profile using CMD_GET_REQ:

Start signal	Command	Length	Settings index	CS
0x02	0x0A	0x01	0x01	0x08

Response CMD_GET_CNF: Successfully read out the radio as 2.

Start signal	Command 0x40	Length	Status	Parameter	CS
0x02	0x4A	0x02	0x00	0x02	0x48

8.2.3. RADIO_DefaultRfTXPower: Configure the RF TX-power

Settings index	Designation	Permissible values	Default value	Permissions	Number of Bytes
2	RADIO_DefaultRfTXPower	0 - 14	14	read/write	1

This user setting defines the radio output power of the module. The user settings parameter RADIO_DefaultRfTXPower is entered as a complement on two. This value represents the power at the radio ic without taking the antenna into account.



The user is responsible for adhering to the statutory regulations for the maximum power output when using this module. In case of the Tarvos-e with an external antenna the antenna gain needs to be taken into account, too.

8.2.3.1. Example 1

Set the radio output power to 0 using the CMD_SET_REQ:

Start signal	Command	Length	Settings index	Parameter	CS
0x02	0x09	0x02	0x02	0x00	0x0B

Response CMD_SET_CNF: Successfully modified the setting.

Start signal	Command 0x40	Length	Status	CS
0x02	0x49	0x01	0x00	0x4A

8.2.3.2. Example 2

Request the radio output power using CMD_GET_REQ:

Start signal	Command	Length	Settings index	CS
0x02	0x0A	0x01	0x02	0x0B

Response CMD_GET_CNF: Successfully read out the radio as 0 dBm.

Start signal	Command 0x40	Length	Status	Parameter	CS
0x02	0x4A	0x02	0x00	0x00	0x48

8.2.4. RADIO_DefaultRfChannel: Configure the RF channel

Settings index	Designation	Permissible values	Default value	Permissions	Number of Bytes
3	RADIO_DefaultRfChannel	0 - 140	106	read/write	1

This user setting determines the wireless channel of the module to be used after a reset. The dependence between channel and frequency is as follows:

$$Channel_{RF} = \frac{Frequency_{RF} - 863 \text{ MHz}}{0.050 \text{ MHz}} \quad (1)$$

or

$$Frequency_{RF} = 863 \text{ MHz} + Channel_{RF} \times 0.050 \text{ MHz} \quad (2)$$

Check chapter 10.1 for more information.



The user is responsible for adhering to the statutory regulations for the frequency and spectrum use when using this module.

8.2.4.1. Example 1

Set the radio channel to 110 (0x6E) using the CMD_SET_REQ:

Start signal	Command	Length	Settings index	Parameter	CS
0x02	0x09	0x02	0x03	0x6E	0x64

Response CMD_SET_CNF: Successfully modified the setting.

Start signal	Command 0x40	Length	Status	CS
0x02	0x49	0x01	0x00	0x4A

8.2.4.2. Example 2

Request the radio channel using CMD_GET_REQ:

Start signal	Command	Length	Settings index	CS
0x02	0x0A	0x01	0x03	0x0A

Response CMD_GET_CNF: Successfully read out the radio as 110 (0x6E).



Start signal	Command 0x40	Length	Status	Parameter	CS
0x02	0x4A	0x02	0x00	0x6E	0x24

8.2.5. MAC_DefaultAddressMode: Configure the address mode

Settings index	Designation	Permissible values	Default value	Permissions	Number of Bytes
4	MAC_DefaultAddressMode	0 - 3	0	read/write	1

This setting defines the address mode of the module. The following modes have been implemented:

No addressing (mode 0): Each module receives the transmitted RF telegram and delivers the received data to the host system via UART. No address information is transmitted in the radio telegram.

1-byte address (mode 1): The receiving module only delivers the data to the host system via UART,

- if the 1 Byte destination address configured at the sender corresponds to the 1 Byte source address of the receiver (MAC_SourceAddr) or
- if the destination broadcast address 255 was specified.

Both, the destination address and the source address are transmitted in the wireless telegram (total = 2 Bytes).

2-Bytes address (mode 2): The receiving module only delivers the data to the host system via UART,

- if both the destination network id and the 1 Byte destination address configured at the sender correspond to the source addresses of the receiver (MAC_SourceNetID and 1 Byte MAC_SourceAddr) or
- if the destination broadcast address 255 and/or network broadcast id 255 was specified.

A total of 4 Bytes of address information are transmitted in the wireless telegram.

3-Bytes address (mode 3): The receiving module only delivers the data to the host system via UART,

- if both the destination network id and the 2 Byte destination address configured at the sender correspond to the source addresses (MAC_SourceNetID and 2 Byte MAC_SourceAddr) of the receiver or
- if the destination broadcast address 65535 and network broadcast id 255 was specified.

A total of 6 Bytes of address information are transmitted in the wireless telegram.



In address mode 0, the use of wireless acknowledgement will cause problems if several wireless modules are addressed simultaneously. Therefore, no ACK is requested when using address mode 0 or when having any broadcast address in the frame (destination net ID and/or destination address). The user shall also not set `MAC_NumRetrys` $\neq$ 0 in address mode 0.



In address mode 0, the double packet detection will ignore concurrently received packets with the same sequence number. It's advisable to use at least address mode 1 in networks with more than 2 members and to configure the sender's addresses uniquely across the network.



The receiver and transmitter modules must always operate in the same address mode! Otherwise, the receiver cannot interpret the received data packet, meaning that the packet will be discarded!

8.2.5.1. Example 1

Set the address mode to 2 using the `CMD_SET_REQ`:

Start signal	Command	Length	Settings index	Parameter	CS
0x02	0x09	0x02	0x04	0x02	0x0F

Response `CMD_SET_CNF`: Successfully modified the setting.

Start signal	Command 0x40	Length	Status	CS
0x02	0x49	0x01	0x00	0x4A

8.2.5.2. Example 2

Request the address mode using `CMD_GET_REQ`:

Start signal	Command	Length	Settings index	CS
0x02	0x0A	0x01	0x04	0x0D

Response `CMD_GET_CNF`: Successfully read out the address mode as 1.

Start signal	Command 0x40	Length	Status	Parameter	CS
0x02	0x4A	0x02	0x00	0x01	0x4B

8.2.6. MAC_NumRetrys: Configure the number of retries

Settings index	Designation	Permissible values	Default value	Permissions	Number of Bytes
6	MAC_NumRetrys	0 - 255	0	read/write	1

This user setting determines the maximum number of wireless transmission retries. If this parameter is set to a value other than zero, the receiver module will automatically be prompted to send a wireless ACK.



Note that sending ACKs additionally increases the traffic and will have influence on the duty-cycle, which can be crucial for CE compliance.



This parameter shall only be enabled (i.e. set to another value other than 0) if the parameter address mode selects a value of 1, 2 or 3 and the customer has configured unique addresses for the entire network. A use of broadcast messages (destination network ID and/or destination address) is not allowed when MAC_NumRetrys is set to any value not equal to 0.

8.2.6.1. Example 1

Set the transmission retry number to 1 using the CMD_SET_REQ:

Start signal	Command	Length	Settings index	Parameter	CS
0x02	0x09	0x02	0x06	0x01	0x0E

Response CMD_SET_CNF: Successfully modified the setting.

Start signal	Command	Length	Status	CS
0x02	0x49	0x01	0x00	0x4A

8.2.6.2. Example 2

Request the number of retries using CMD_GET_REQ:

Start signal	Command	Length	Settings index	CS
0x02	0x0A	0x01	0x06	0x0F

Response CMD_GET_CNF: Successfully read out the number of retries as 3.

Start signal	Command 0x40	Length	Status	Parameter	CS
0x02	0x4A	0x02	0x00	0x03	0x49

8.2.7. MAC_DefaultDestNetID: Configure the destination network ID

Settings index	Designation	Permissible values	Default value	Permissions	Number of Bytes
7	MAC_DefaultDestNetID	0 - 255	255	read/write	1

This user setting specifies the default destination network ID, which is used in address modes 2 and 3. If the special broadcast ID and the broadcast address are set to 255, the packets will be received by all network participants. Its volatile runtime settings can be modified with the command CMD_SET_DESTNETID_REQ at runtime.

8.2.7.1. Example 1

Set the default destination network ID to 1 using the CMD_SET_REQ:

Start signal	Command	Length	Settings index	Parameter	CS
0x02	0x09	0x02	0x07	0x01	0x0F

Response CMD_SET_CNF: Successfully modified the setting.

Start signal	Command 0x40	Length	Status	CS
0x02	0x49	0x01	0x00	0x4A

8.2.7.2. Example 2

Request the default destination network ID using CMD_GET_REQ:

Start signal	Command	Length	Settings index	CS
0x02	0x0A	0x01	0x07	0x0E

Response CMD_GET_CNF: Successfully read out the default destination network ID as 0.

Start signal	Command 0x40	Length	Status	Parameter	CS
0x02	0x4A	0x02	0x00	0x00	0x4A

8.2.8. MAC_DefaultDestAddr: Configure the destination address

Settings index	Designation	Permissible values	Default value	Permissions	Number of Bytes
8	MAC_DefaultDestAddr	0 - 65535	65535	read/write	1-2

This user setting specifies the destination address, which is used in address modes 1, 2 and 3. If a broadcast address (255 in address modes 1 and 2 or 65535 in address mode 3) is used, the packets will be received by all network participants or by participants in the same network ID. Its volatile runtime settings can be modified with the command CMD_SET_DESTADDR_REQ at runtime.

8.2.8.1. Example 1

Set the default destination address to 1 using the CMD_SET_REQ. If only one-byte parameter size is used, the LSB is set to the value of the parameter and the MSB is automatically written to 0xFF.

Start signal	Command	Length	Settings index	Parameter	CS
0x02	0x09	0x02	0x08	0x01	0x00

Response CMD_SET_CNF: Successfully modified the setting.

Start signal	Command 0x40	Length	Status	CS
0x02	0x49	0x01	0x00	0x4A

8.2.8.2. Example 2

Set the default destination address to 256 (0x0100) using the CMD_SET_REQ. LSB = 0x00, MSB = 0x01. The MSB of the address is used in address mode 3 only. The 2-byte parameter field has the order LSB first.

Start signal	Command	Length	Settings index	Parameter	CS
0x02	0x09	0x03	0x08	0x00 0x01	0x01

Response CMD_SET_CNF: Successfully modified the setting.

Start signal	Command 0x40	Length	Status	CS
0x02	0x49	0x01	0x00	0x4A

8.2.8.3. Example 3

Request the default destination address using CMD_GET_REQ:

Start signal	Command	Length	Settings index	CS
0x02	0x0A	0x01	0x08	0x01

Response CMD_GET_CNF: Successfully read out the default destination address as 0 (0x0000). The 2-byte parameter has the order LSB first. The return value of this settings index is always read as 2-byte parameter.

Start signal	Command 0x40	Length	Status	Parameter	CS
0x02	0x4A	0x03	0x00	0x00 0x00	0x4B

8.2.9. MAC_SourceNetID: Configure the source network ID

Settings index	Designation	Permissible values	Default value	Permissions	Number of Bytes
10	MAC_SourceNetID	0 - 254	0	read/write	1

This user setting specifies the source network ID to be used in address modes 2 and 3. Setting the Source Net ID to Broadcast (255) is not allowed.

8.2.9.1. Example 1

Set the source network ID to 1 using the CMD_SET_REQ:

Start signal	Command	Length	Settings index	Parameter	CS
0x02	0x09	0x02	0x0A	0x01	0x02

Response CMD_SET_CNF: Successfully modified the setting.

Start signal	Command 0x40	Length	Status	CS
0x02	0x49	0x01	0x00	0x4A

8.2.9.2. Example 2

Request the source network ID using CMD_GET_REQ:

Start signal	Command	Length	Settings index	CS
0x02	0x0A	0x01	0x0A	0x03

Response CMD_GET_CNF: Successfully read out the source network ID as 2.

Start signal	Command 0x40	Length	Status	Parameter	CS
0x02	0x4A	0x02	0x00	0x02	0x48

8.2.10. MAC_SourceAddr: Configure the source address

Settings index	Designation	Permissible values	Default value	Permissions	Number of Bytes
11	MAC_SourceAddr	0 - 65534	0	read/write	1-2

This user setting specifies the source device address to be used in address modes 1, 2 and 3. The LSB corresponds to the first byte in "parameter"; the MSB (if used) to the second byte. The broadcast address 0xFF (255) or 0xFFFF (65535) must not be used for the source address (LSB, LSB+MSB) and source network ID parameters.

8.2.10.1. Example 1

Set the source address to 1 (this will set the LSB to 0x01, the MSB is automatically set to 0xFF) using the CMD_SET_REQ:

Start signal	Command	Length	Settings index	Parameter	CS
0x02	0x09	0x02	0x0B	0x01	0x03

Response CMD_SET_CNF: Successfully modified the setting.

Start signal	Command 0x40	Length	Status	CS
0x02	0x49	0x01	0x00	0x4A

8.2.10.2. Example 2

Set the source address to 256 (LSB = 0x00, MSB = 0x01) using the CMD_SET_REQ. The 2-byte parameter is to be used LSB first.

Start signal	Command	Length	Settings index	Parameter	CS
0x02	0x09	0x03	0x0B	0x00 0x01	0x02

Response CMD_SET_CNF: Successfully modified the setting.

Start signal	Command 0x40	Length	Status	CS
0x02	0x49	0x01	0x00	0x4A

8.2.10.3. Example 3

Request the source address using CMD_GET_REQ:

Start signal	Command	Length	Settings index	CS
0x02	0x0A	0x01	0x0B	0x02

Response CMD_GET_CNF: Successfully read out the source address as 2 (0x0002). The 2-byte parameter is to be used LSB first.

Start signal	Command 0x40	Length	Status	Parameter	CS
0x02	0x4A	0x03	0x00	0x02 0x00	0x49

8.2.11. OpMode: Default operating mode of the module

Settings index	Designation	Permissible values	Default value	Permissions	Number of Bytes
14	OpMode	0,16	16	read, write	1

The OpMode configures the operating mode of the module after start-up. A OpMode of 0x10 (16) represents the command mode. OpMode 0x00 indicates transparent mode.



The *MODE_1* pin has a higher priority than OpMode. Therefore, if OpMode is configured as 0x10 (command mode) and *MODE_1* pin has a HIGH level during start-up, the module will start in transparent mode.

8.2.11.1. Example 1

Set the operating mode to command mode (0x10) using the CMD_SET_REQ:

Start signal	Command	Length	Settings index	Parameter	CS
0x02	0x09	0x02	0x0E	0x10	0x17

Response CMD_SET_CNF: Successfully modified the setting.

Start signal	Command 0x40	Length	Status	CS
0x02	0x49	0x01	0x00	0x4A

8.2.11.2. Example 2

Request the operation mode using CMD_GET_REQ:

Start signal	Command	Length	Settings index	CS
0x02	0x0A	0x01	0x0E	0x07

Response CMD_GET_CNF: Successfully read out that the operation mode is command mode (0x10).

Start signal	Command 0x40	Length	Status	Parameter	CS
0x02	0x4A	0x02	0x00	0x10	0x5A

8.2.12. OpMode_Flags: Configure transmission trigger for transparent mode

Settings index	Designation	Permissible values	Default value	Permissions	Number of Bytes
18	OpMode_Flags	See description	0x0C	read/write	1

Selects and configures the trigger to start the radio transmission for the transparent mode. Various triggers can be activated simultaneously. Only used in transparent mode.

Independent of the configuration of OpMode_Flags, a radio transmission will be triggered whenever the maximum packet size is reached. The maximum packet size depends on RADIO_DefaultRfProfile.

Bit no.	Filter	Description
0	0x01	Set this bit to '1' to include the ETX characters in the payload of the radio frame. Otherwise ETX characters will be removed before radio transmission. Only used when bit 1 is set to '1'.
1	0x02	Set this bit to '1' to enable ETX character as trigger for radio transmission. See UART_ETX_Character0 and UART_ETX_Character1 to configure ETX characters.
2	0x04	Set this bit to '1' to enable timeout as trigger for radio transmission. See UART_Timeout to configure timeout.
3	0x08	Set this bit to '1' to set length of ETX character to two bytes. Set this bit to '0' to set length to one byte. Only used when bit 1 is set to '1'.
4-7	0xF0	Reserved for future use. All reserved bits shall be set to '0'.

8.2.12.1. Example 1

Set the parameter OpMode_Flags to 0x04, which means that the transmission starts when the maximum packet size or timeout has been reached.

Command:

Start signal	Command	Length	Settings index	Parameter	CS
0x02	0x09	0x02	0x12	0x04	0x1F

Response CMD_SET_CNF: Successfully modified the setting.

Start signal	Command 0x40	Length	Status	CS
0x02	0x49	0x01	0x00	0x4A

8.2.12.2. Example 2

Request the flags using CMD_GET_REQ:

Start signal	Command	Length	Settings index	CS
0x02	0x0A	0x01	0x12	0x1B

Response CMD_GET_CNF: Successfully read out the value of OpMode_Flags. A value of 0x04 indicates timeout as trigger for radio transmissions.

Start signal	Command 0x40	Length	Status	Parameter	CS
0x02	0x4A	0x03	0x00	0x04	0x4F

8.2.13. UART_Timeout: Configure timeout for transparent mode

Settings index	Designation	Permissible values	Default value	Permissions	Number of Bytes
21	UART_Timeout	5 - 255	5	read,write	1

UART_Timeout is used when OpMode_Flags is configured to use timeout as radio transmission trigger in transparent mode. If the module receives no new byte within the defined UART_Timeout and the buffer is not empty, a radio transmission starts. UART_Timeout is stated in milliseconds. UART_Timeout is only used in transparent mode.

8.2.13.1. Example 1

Set the timeout to 5 ms using the CMD_SET_REQ:

Start signal	Command	Length	Settings index	Parameter	CS
0x02	0x09	0x02	0x15	0x05	0x19

Response CMD_SET_CNF: Successfully modified the setting.

Start signal	Command 0x40	Length	Status	CS
0x02	0x49	0x01	0x00	0x4A

8.2.13.2. Example 2

Request the timeout using CMD_GET_REQ:

Start signal	Command	Length	Settings index	CS
0x02	0x0A	0x01	0x15	0x1C

Response CMD_GET_CNF: Successfully read out the timeout of 5 ms.

Start signal	Command 0x40	Length	Status	Parameter	CS
0x02	0x4A	0x02	0x00	0x05	0x4F

8.2.14. UART_ETX_Character0: Configure ETX characters for transparent mode

Settings index	Designation	Permissible values	Default value	Permissions	Number of Bytes
19	UART_ETX_Character0	See description	0x0D	read/write	1 or 2

UART_ETX_Character0 is used when OpMode_Flags is configured to use ETX characters as radio transmission trigger in transparent mode. If the module receives the defined ETX_Characters within the received data over UART and the buffer is not empty, a radio transmission starts. When using a parameter length of 2, UART_ETX_Character0 and UART_ETX_Character1 can be set simultaneously (see example 2 below). However, the parameters have to be read out separately.

UART_ETX_Character0 is only used in transparent mode.

8.2.14.1. Example 1

Set the parameter UART_ETX_Character0 to 0x0D ('r') using CMD_SET_REQ.

Command:

Start signal	Command	Length	Settings index	Parameter	CS
0x02	0x09	0x02	0x13	0x0D	0x17

Response CMD_SET_CNF: Successfully modified the setting.

Start signal	Command 0x40	Length	Status	CS
0x02	0x49	0x01	0x00	0x4A

8.2.14.2. Example 2

Set the parameter UART_ETX_Character0 to 0x0D ('r') and UART_ETX_Character1 to 0x0A ('\n') using CMD_SET_REQ.

Command:

Start signal	Command	Length	Settings index	Parameter	CS
0x02	0x09	0x03	0x13	0x0D 0x0A	0x1C

Response CMD_SET_CNF: Successfully modified the setting.

Start signal	Command 0x40	Length	Status	CS
0x02	0x49	0x01	0x00	0x4A

8.2.14.3. Example 3

Request the ETX-character using CMD_GET_REQ:

Start signal	Command	Length	Settings index	CS
0x02	0x0A	0x01	0x13	0x1A

Response CMD_GET_CNF: Successfully read out the value 0x0D ('\r') of UART_ETX_Character0.

Start signal	Command 0x40	Length	Status	Parameter	CS
0x02	0x4A	0x03	0x00	0x0D	0x46

8.2.15. UART_ETX_Character1: Configure ETX character for transparent mode

Settings index	Designation	Permissible values	Default value	Permissions	Number of Bytes
20	UART_ETX_Character1	See description	0x0A	read/write	1

UART_ETX_Character1 is used when OpMode_Flags is configured to use two ETX-characters as radio transmission trigger in transparent mode. If the module receives the defined ETX characters within the received data over UART and the buffer is not empty, a radio transmission starts. UART_ETX_Character1 is only used in transparent mode.

8.2.15.1. Example 1

Set the parameter UART_ETX_Character1 to 0x0A ('\n') using CMD_SET_REQ.

Command:

Start signal	Command	Length	Settings index	Parameter	CS
0x02	0x09	0x02	0x14	0x0A	0x17

Response CMD_SET_CNF: Successfully modified the setting.

Start signal	Command 0x40	Length	Status	CS
0x02	0x49	0x01	0x00	0x4A

8.2.15.2. Example 2

Request the ETX-character using CMD_GET_REQ:

Start signal	Command	Length	Settings index	CS
0x02	0x0A	0x01	0x14	0x1D

Response CMD_GET_CNF: Successfully read out the value 0x0A ('\n') of UART_ETX_Character1.

Start signal	Command 0x40	Length	Status	Parameter	CS
0x02	0x4A	0x02	0x00	0x0A	0x40

8.2.16. CfgFlags: Configure the configuration flags of the module

Settings index	Designation	Permissible values	Default value	Permissions	Number of Bytes
15	CfgFlags	See description	0	read/write	2

This parameter is used for the general module configuration.



Repeater and sniffer mode cannot be enabled at the same time. A module configured as sniffer will not send any ACKs, even if requested by the sender.

Bit no.	Filter	Description
0	0x0001	Set this bit to '1' to enable the sniffer mode. The sniffer mode will ignore all destination addresses in the radio frames and forward any compatible message into a CMD_DATAEX_IND. Not to be used when repeater mode is enabled or MAC_NumRetrys is not equal to 0.
1	0x0002	Set this bit to '1' to enable the duty cycle tracker mode. In this mode CMD_DUTYCYCLE_IND messages are output by the module, when the module transmitted data on the radio. This message contains the time needed to transmit the radio data, which can be used by the host to track its duty cycle.
2 - 15	0xFFFF	Reserved for future use. All reserved bits '0'.

8.2.16.1. Example 1

Enable the sniffer mode by setting the CfgFlags parameter value to 0x0001 using the CMD_SET_REQ. The 2-byte parameter is to be used LSB first.

Start signal	Command	Length	Settings index	Parameter	CS
0x02	0x09	0x03	0x0F	0x01 0x00	0x06

Response CMD_SET_CNF: Successfully modified the setting.

Start signal	Command	Length	Status	CS
0x02	0x49	0x01	0x00	0x4A

8.2.16.2. Example 2

Request the configuration flags using CMD_GET_REQ:

Start signal	Command	Length	Settings index	CS
0x02	0x0A	0x01	0x0F	0x06

Response CMD_GET_CNF: Successfully read out the value of CfgFlags. The 2-byte parameter is to be used LSB first. A parameter value 0x0000 indicates that the sniffer mode is disabled.

Start signal	Command 0x40	Length	Status	Parameter	CS
0x02	0x4A	0x03	0x00	0x00 0x00	0x4B

8.2.17. RpFlags: Configure the repeater flags of the module

Settings index	Designation	Permissible values	Default value	Permissions	Number of Bytes
16	RpFlags	See description	0	read/write	2

This parameter is used for the repeater configuration. See chapter 13 for more information about the repeater mode.



Repeater and sniffer mode cannot be enabled at the same time.



The repeater function shall not be enabled in radio profile 4.



The user is responsible for adhering to the statutory regulations for the frequency and spectrum use when using the repeater mode with this module. Especially the duty-cycle of each repeating network node must be checked and controlled by the end system application in respect to country-specific regulations.

Bit no.	Filter	Description
0	0x0001	Set this bit to '1' to enable the repeater mode.
1 - 15	0xFFFFE	Reserved for future use. All reserved bits '0'.

8.2.17.1. Example 1

Enable the repeater mode by setting the RpFlags parameter value to 0x0001 using the CMD_SET_REQ. The 2-byte parameter is to be used LSB first.

Start signal	Command	Length	Settings index	Parameter	CS
0x02	0x09	0x03	0x10	0x01 0x00	0x19

Response CMD_SET_CNF: Successfully modified the setting.

Start signal	Command 0x40	Length	Status	CS
0x02	0x49	0x01	0x00	0x4A

8.2.17.2. Example 2

Request the repeater flags using CMD_GET_REQ:

Start signal	Command	Length	Settings index	CS
0x02	0x0A	0x01	0x10	0x19

Response CMD_GET_CNF: Successfully read out the value of RpFlags. The 2-byte parameter is to be used LSB first. A parameter value 0x0000 indicates that the repeater mode is disabled. A value of 0x0001 indicates that the repeater mode is enabled.

Start signal	Command 0x40	Length	Status	Parameter	CS
0x02	0x4A	0x03	0x00	0x00 0x00	0x4B

8.2.18. RP_NumSlots: Configure the repeater data base

Settings index	Designation	Permissible values	Default value	Permissions	Number of Bytes
17	RP_NumSlots	1 -255	32	read/write	1

An 8 bit field that contains the number of time slots to be used for the packet repetition. When using several repeater devices in a single network, repeated data packets may collide on the frequency channel, when all repeater devices send the received packet at the same time. To avoid this, the frequency channel is divided in RP_NumSlots time slots, where each repeater chooses a certain slot randomly.



Repeaters must be carefully positioned within a network setup, in order to prevent loops and additional latency. It is not an intended use of this product to enable repeater mode on any or, worst case, all devices in the network.

The smallest number of time slots that is needed depends on the network structure and the number of the repeaters used. Assume there are NumRP repeater devices in the range of a sending device. The probability that two repeated packets collide can be calculated by:

$$1 - \frac{RP_NumSlots!}{RP_NumSlots^{NumRP} \times (RP_NumSlots - NumRP)!} \quad (3)$$

Common values are:

NumRP	RP_NumSlots	Collision probability
2	32	3.1%
3	32	9.2%
4	32	17.7%
5	64	14.8%
6	64	21.5%
7	128	15.4%

In the example network shown in figure 8, there are only two repeaters that can conflict with each other. Repeater 2 and 3 are forwarding the packet received from sender 1 "at the same time". Thus, NumRP equals 2 and RP_NumSlots equal 32 is sufficient to have a collision probability of less than 5%. The time delay used by the repeater device can be determined as the time needed to send one packet (see table 13) times a random number between one and RP_NumSlots.

Example:

In RADIO_DefaultRfProfile 0 the maximum send time for one packet is about 40 ms. If we use 32 RP_NumSlots, the packet is forwarded latest after 32×40 ms=1280 ms.

8.2.18.1. Example 1

Set the RP_NumSlots to 64 (0x40) using the CMD_SET_REQ.

Start signal	Command	Length	Settings index	Parameter	CS
0x02	0x09	0x02	0x11	0x40	0x58

Response CMD_SET_CNF: Successfully modified the setting.

Start signal	Command 0x40	Length	Status	CS
0x02	0x49	0x01	0x00	0x4A

8.2.18.2. Example 2

Request the number of repeater slots using CMD_GET_REQ:

Start signal	Command	Length	Settings index	CS
0x02	0x0A	0x01	0x11	0x18

Response CMD_GET_CNF: Successfully read out the number of repeater slots as 32 (0x20).

Start signal	Command 0x40	Length	Status	Parameter	CS
0x02	0x4A	0x02	0x00	0x20	0x6A

8.2.19. LBT_ObservationPeriod: Configure the observation period for LBT

Settings index	Designation	Permissible values	Default value	Permissions	Number of Bytes
26	LBT_ObservationPeriod	0 - 15	0	read/write	1

The LBT_ObservationPeriod defines the duration to listen on the channel, to determine if it is busy or free. If it is set to 0, then LBT is disabled. Otherwise, it is enabled with the specified observation period. LBT_ObservationPeriod is stated in milliseconds.



Activating LBT will reduce the throughput of the network, depending on the selected observation period.

8.2.19.1. Example 1

Set LBT_ObservationPeriod to 15 (0x0F) using the CMD_SET_REQ.

Start signal	Command	Length	Settings index	Parameter	CS
0x02	0x09	0x02	0x1A	0x0F	0x1C

Response CMD_SET_CNF: Successfully modified the setting.

Start signal	Command 0x40	Length	Status	CS
0x02	0x49	0x01	0x00	0x4A

8.2.19.2. Example 2

Request LBT_ObservationPeriod using CMD_GET_REQ:

Start signal	Command	Length	Settings index	CS
0x02	0x0A	0x01	0x1A	0x13

Response CMD_GET_CNF: Successfully read out the observation period for LBT as 14 (0x0E) ms.

Start signal	Command 0x40	Length	Status	Parameter	CS
0x02	0x4A	0x02	0x00	0x0E	0x44

8.2.20. LBT_Threshold: Configure the RSSI threshold for LBT

Settings index	Designation	Permissible values	Default value	Permissions	Number of Bytes
27	LBT_Threshold	-100 - -45	-80 (0xB0)	read/write	1

LBT_Threshold defines the minimum RSSI value during LBT_ObservationPeriod to consider the channel to be busy. LBT_Threshold is stated in dBm.



LBT_Threshold is only used when LBT is enabled (LBT_ObservationPeriod is set to a value other than 0).
Since this value is negative, it is expressed in two's complement.

8.2.20.1. Example 1

Set LBT_Threshold to -60 (0xC4) dBm using the CMD_SET_REQ.

Start signal	Command	Length	Settings index	Parameter	CS
0x02	0x09	0x02	0x1B	0xC4	0xD6

Response CMD_SET_CNF: Successfully modified the setting.

Start signal	Command 0x40	Length	Status	CS
0x02	0x49	0x01	0x00	0x4A

8.2.20.2. Example 2

Request LBT_Threshold using CMD_GET_REQ:

Start signal	Command	Length	Settings index	CS
0x02	0x0A	0x01	0x1B	0x12

Response CMD_GET_CNF: Successfully read out the threshold for LBT as -95 (0xA1) dBm.

Start signal	Command 0x40	Length	Status	Parameter	CS
0x02	0x4A	0x02	0x00	0xA1	0xEB

8.2.21. FactorySettings: Read out the factory settings

Settings index	Designation	Permissible values	Default value	Permissions	Number of Bytes
32	FactorySettings	-	-	read	8

This parameter defines the factory settings of the module.

byte no.	Description
3 : 0	Serial number: 3 byte ID (LSB first), 1 byte PID
6 : 4	Hardware version: layout, BOM, reserved
7	Frequency correction factor

8.2.21.1. Example 1

Request the factory settings of the module using CMD_GET_REQ:

Start signal	Command	Length	Settings index	CS
0x02	0x0A	0x01	0x20	0x29

Response CMD_GET_CNF: Successfully read out the FactorySettings.

Start signal	Command 0x40	Length	Status	Parameter	CS
0x02	0x4A	0x09	0x00	0x01 0x00 0x00 0x74 0x00 0x03 0x02 0x00	0x35

Successfully returned the following factory settings, the order of the multi byte parameters was changed to MSB first to be converted into decimal numbers later:

- Serial number: 0x74.000001 (116.000001) with PID 0x74 (116) and SN 0x000001 (1)
- Hardware version 0x02 0x03 0x00 (2.3.0)
- Frequency correction factor of 0x00 (0)

8.2.22. FirmwareVersion: Read out the firmware version

Settings index	Designation	Permissible values	Default value	Permissions	Number of Bytes
33	FirmwareVersion	-	-	read	3

This parameter defines the version of the firmware currently running on the module.

8.2.22.1. Example 1

Request the factory settings of the module using CMD_GET_REQ:

Start signal	Command	Length	Settings index	CS
0x02	0x0A	0x01	0x21	0x28

Response CMD_GET_CNF: Successfully read out the firmware version as 2.1.0. The sequence inside the field "Parameter" is patch, minor, major.

Start signal	Command 0x40	Length	Status	Parameter	CS
0x02	0x4A	0x04	0x00	0x00 0x01 0x02	0x4F

9. Timing parameters

9.1. Reset behavior

Following a reset, a `CMD_RESET_IND` and a stable low level on the `BUSY` pin signalizes that the module is ready for operation. During restart, the `BUSY` may be pulled to GND level for a short time ($< 100 \mu\text{s}$, see figure 6) until it is configured accordingly by the application on the module.

9.1.1. Reset via /RESET pin

To force a module restart by means of the `/RESET` pin, it must first be drawn to low for at least 1 ms. After the pin is released, the module will reboot, indicate a `CMD_RESET_IND`.



Note that the selected UART baud rate will introduce a latency for transmitting the 5-byte packet at module start-up.

Recommended procedure: After the `/RESET` pin is released, wait for up to 200 ms + UART transmission time for the `CMD_RESET_IND` packet (value is to be adopted for the selected UART baud rate) and for the stable low level on the `BUSY` pin.



This section applies only to a situation where the VDD is stable and the module was already running. Additional timings are needed when VDD was just applied to the module. See chapter 4.2

9.1.2. Reset as result of a serious error condition

If the module runs into a serious error condition, a software reset will be executed. In this case, the module starts up (this includes sending a `CMD_RESET_IND`) automatically and can then be used again. The volatile runtime settings are reset to default values. Therefore, the host needs to detect the start-up indication and implement/reconfigure the module's volatile settings, if this event was detected.

9.2. Latencies when leaving standby or shutdown

The indication `CMD_RESET_IND` or `CMD_STANDBY_IND` (5 Bytes in total) are written before the `BUSY` pin is pulled back to low level. Therefore, the start-up time is also dependent on the UART baud rate. The time presented here was measured with the UART default setting of 115200 Baud, 8n1.

9.2.1. Wake-up latency from standby

The wake-up time from standby is 1.6 ms.

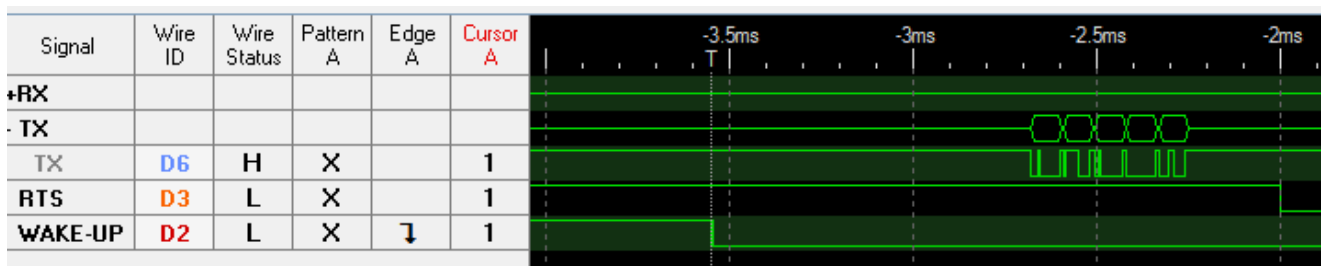


Figure 6: Wake-up from standby

9.2.2. Wake-up latency from shutdown

The wake-up time from shutdown is 5 ms.

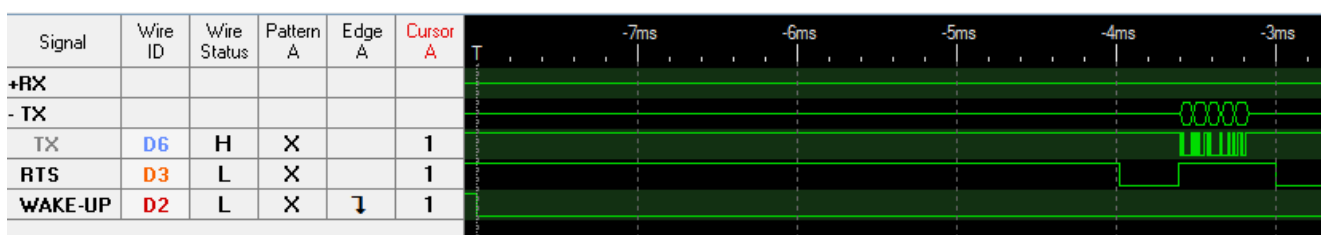


Figure 7: Wake-up from shutdown

9.3. Latencies during data transfer / packet generation

The data transfer is always buffered, i.e. data received via UART is buffered in the module until a specific event occurs (i.e. packet completed with the CS field of a command). Subsequently, the UART reception is interrupted (flow control with *BUSY* signal) and the payload data is passed to the internal memory of the wireless transceiver (FIFO).

By using several UART buffers, the time during which the UART is not receiving can be minimized.

The wireless transmission starts as soon as the first complete data packet is available in the transceiver memory. During the continuous wireless transmission, the remaining payload data is transmitted byte by byte on the radio. On the receiver side, the buffer is read as soon as an incoming packet is detected. The entire radio frame is buffered in the radio buffer and processed once the frame was checked against bit errors.

If the module detects a packet that requires an ACK, the ACK is sent directly after the full packet reception. The channel access method is always deactivated for any ACKs.

10. Radio parameters

The default radio parameters are determined by the values of `RADIO_DefaultRfProfile`, `RADIO_DefaultRfChannel` and `RADIO_DefaultRfTXPower` in the user settings. These non-volatile parameters can be modified using `CMD_SET_REQ`. To modify their volatile counterparts the commands `CMD_SET_PAPOWER_REQ` and `CMD_SET_CHANNEL_REQ` can be used.



The parameter must be chosen with prudence to reach good functionality and compliance with valid regulatory requirements such as the EN 300 220 in the European Union or the FCC in the United States of America. The user of this module is solely responsible for adhering to all applicable statutory regulations.



The module is tested through an accredited test lab to conform to the requirements of the RED. The module complies to receiver category 2.

This means, that mounted on its EV-board it complies to the requirements of the RED. However, conformance of the end-device depends also but not limited to the radiated power of the end-device. Which strongly depends on the selected antenna, the pcb design, the wiring to the antenna and the quality of the power supply. Thus, it is highly recommended that the end-device manufacturer verifies the radiated power characteristic on the end application.

An important aspect to comply with the radio regulatory is to adhere to the requirements of the duty cycle. As defined in EN 300 220, the duty cycle is the ratio expressed as a percentage of the cumulative duration of transmission T_{on} within an observation time interval of T_{obs} . $DC = (\frac{T_{on}}{T_{obs}}) F_{obs}$ on an observation bandwidth F_{obs} . Unless otherwise specified, T_{obs} is 1 hour and the observation bandwidth F_{obs} is the operational frequency band.



There are no mechanisms for constraining the duty cycle in the firmware. The user is fully responsible for the compliance of the duty cycle and implementing according mechanisms in the end-device. The `CMD_DUTYCYCLE_IND` message returns the consumed time, when data has been transmitted on radio. This can be used to track the duty cycle.

The frequency channels of the module can be selected from a 50 kHz grid. Not all channels are permissible, depending on the selected profile, output power and antenna (radio profile, radio TX power and radio channel).



Depending on the chosen radio profile the channel spacing declared in table 14, chapter 10.1 has to be applied.

10.1. Channel assignment



For maintenance reasons the following tables are taken from Tarvos-III, the RFProfile "res." mentioned in this table is therefore to be ignored when using a Tarvos-e.

Sub Band	Channel	Frequency MHz	res.	Profile 0,4	Profile 2	Profile 5
	Required channel spacing		50 kHz	100 kHz	200 kHz	600 kHz
Band K 863 MHz - 865 MHz ≤ 14 dBm The whole band except for audio & video applications limited to 300 kHz duty cycle ≤ 0.1% or PSA	0	863.00	Band limit			
	1	863.05	K	K	-	-
	2	863.10	K	*	K	-
	3	863.15	K	K	*	-
	4	863.20	K	*	*	-
	5	863.25	K	K	*	-
	6	863.30	K	*	K	K
	7	863.35	K	K	*	*
	8	863.40	K	*	*	*
	9	863.45	K	K	*	-
	10	863.50	K	*	K	*
	11	863.55	K	K	*	*
	12	863.60	K	*	*	*
	13	863.65	K	K	*	*
	14	863.70	K	*	K	*
	15	863.75	K	K	*	*
	16	863.80	K	*	*	*
	17	863.85	K	K	*	*
	18	863.90	K	*	K	K
	19	863.95	K	K	*	*
	20	864.00	K	*	*	*
	21	864.05	K	K	*	*
	22	864.10	K	*	K	*
	23	864.15	K	K	*	*
	24	864.20	K	*	*	*
	25	864.25	K	K	*	*
	26	864.30	K	*	K	*
	27	864.35	K	K	*	*
	28	864.40	K	*	*	*
	29	864.45	K	K	*	*
	30	864.50	K	*	K	*
	31	864.55	K	K	*	*
	32	864.60	K	*	*	*
	33	864.65	K	K	*	*
	34	864.70	K	*	K	K
	35	864.75	K	K	*	-
	36	864.80	K	*	*	-
	37	864.85	K	K	*	-
	38	864.90	K	*	K	-
	39	864.95	K	K	-	-
	40	865.00	Band limit			

Sub Band	Channel	Frequency MHz	res.	Profile 0,4	Profile 2	Profile 5
	Required channel spacing		50 kHz	100 kHz	200 kHz	600 kHz
Band L 865 MHz - 868 MHz ≤ 14 dBm -4.5 dBm/100 kHz The power density can be increased to +6.2 dBm/100 kHz if the band of operation is limited to 865 MHz to 868 MHz The whole band except for audio & video applications limited to 300 kHz duty cycle $\leq 1\%$ or PSA Other usage restrictions: DSSS and any techniques other than FHSS.	40	865.00	Band limit			
	41	865.05	L	L	-	-
	42	865.10	L	*	L	-
	43	865.15	L	L	*	-
	44	865.20	L	*	*	-
	45	865.25	L	L	*	-
	46	865.30	L	*	L	L
	47	865.35	L	L	*	*
	48	865.40	L	*	*	*
	49	865.45	L	L	*	*
	50	865.50	L	*	L	*
	51	865.55	L	L	*	*
	52	865.60	L	*	*	*
	53	865.65	L	L	*	*
	54	865.70	L	*	L	*
	55	865.75	L	L	*	*
	56	865.80	L	*	*	*
	57	865.85	L	L	*	*
	58	865.90	L	*	L	L
	59	865.95	L	L	*	*
	60	866.00	L	*	*	*
	61	866.05	L	L	*	*
	62	866.10	L	*	L	*
	63	866.15	L	L	*	*
	64	866.20	L	*	*	*
	65	866.25	L	L	*	*
	66	866.30	L	*	L	*
	67	866.35	L	L	*	*
	68	866.40	L	*	*	*
	69	866.45	L	L	*	*
	70	866.50	L	*	L	L
	71	866.55	L	L	*	*
	72	866.60	L	*	*	*
	73	866.65	L	L	*	*
	74	866.70	L	*	L	*
	75	866.75	L	L	*	*
	76	866.80	L	*	*	*
	77	866.85	L	L	*	*
	78	866.90	L	*	L	*
	79	866.95	L	L	*	*

Sub Band	Channel	Frequency MHz	res.	Profile 0,4	Profile 2	Profile 5
	Required channel spacing		50 kHz	100 kHz	200 kHz	600 kHz
Band L 865 MHz - 868 MHz ≤ 14 dBm -4.5 dBm/100 kHz The power density can be increased to +6.2 dBm/100 kHz if the band of operation is limited to 865 MHz to 868 MHz The whole band except for audio & video applications limited to 300 kHz duty cycle $\leq 1\%$ or PSA Other usage restrictions: DSSS and any techniques other than FHSS.	80	867.00	L	L	*	*
	81	867.05	L	*	*	*
	82	867.10	L	L	L	L
	83	867.15	L	*	*	*
	84	867.20	L	L	-	*
	85	867.25	L	*	*	*
	86	867.30	L	L	L	*
	87	867.35	L	*	*	*
	88	867.40	L	L	*	*
	89	867.45	K	*	*	*
	90	867.50	L	L	L	*
	91	867.55	L	*	*	*
	92	867.60	L	L	*	*
	93	867.65	L	*	*	*
	94	867.70	L	L	L	L
	95	867.75	L	*	*	-
	96	867.80	L	*	*	-
	97	867.85	L	*	*	-
	98	867.90	L	L	L	-
	99	867.95	L	-	-	-
Band M 868 MHz - 868.6 MHz ≤ 14 dBm The whole band except for audio& video applications limited to 300 kHz duty cycle $\leq 1\%$ or PSA	100	868.00	Band limit			
	101	868.05	M	M	-	-
	102	868.10	M	*	M	-
	103	868.15	M	M	*	-
	104	868.20	M	*	*	-
	105	868.25	M	M	*	-
	106	868.30	M	*	M	M
	107	868.35	M	M	*	-
	108	868.40	M	*	*	-
	109	868.45	M	M	*	-
	110	868.50	M	*	M	-
	111	868.55	M	M	-	-
	112	868.60	Band limit			
	113	868.65	Out of band			

Sub Band		Channel	Frequency MHz	res.	Profile 0,4	Profile 2	Profile 5
		Required channel spacing		50 kHz	100 kHz	200 kHz	600 kHz
Band N 868.7 MHz - 869.2 MHz ≤ 14 dBm The whole band except for audio & video applications limited to 300 kHz duty cycle ≤ 0.1% or PSA		114	868.70	Band limit			
		115	868.75	N	N	-	-
		116	868.80	N	*	*	-
		117	868.85	N	N	N	-
		118	868.90	N	*	*	-
		119	868.95	N	N	*	-
		120	869.00	N	*	*	-
		121	869.05	N	N	N	-
		122	869.10	N	*	*	-
		123	869.15	N	N	-	-
		124	869.20	Band limit			
		125	869.25	Out of band			
		126	869.30				
		127	869.35				
Band O 869.4 MHz - 869.65 MHz ≤ 14 dBm duty cycle ≤ 0.1% or PSA	Band P ≤ 27 dBm duty cycle ≤ 10% or PSA	128	869.40	Band limit			
		129	869.45	P	P	-	-
		130	869.50	P	*	P	-
		131	869.55	P	P	*	-
		132	869.60	P	*	-	-
		133	869.65	Band limit			
Band Q 869.7 MHz - 870 MHz ≤ 7 dBm No duty cycle	Band R ≤ 14 dBm duty cycle ≤ 1% or PSA	134	869.70	Band limit			
		135	869.75	Q/R	Q/R	-	-
		136	869.80	Q/R	*	Q/R	-
		137	869.85	Q/R	Q/R	*	-
		138	869.90	Q/R	*	*	-
		139	869.95	Q/R	Q/R	-	-
		140	870.00	Band limit			

Table 14: Channel assignment



The EN 300 220 allows a specific tx duration when the standard complying PSA method is implemented in the module firmware. The standard Tarvos-e firmware does not implement standard compliant PSA. With PSA a transmission time of up to 100 s/h (3.6%) is possible.

K, L, M, N, P, Q, R means that the channel is allowed corresponding to the appropriate EN 300 220 operational frequency band requirements.

- means, that the channel is not allowed.

* means, that the channel in general is allowed, but the above mentioned channel spacing must be fulfilled. In general allowed means, that the occupied channel fits into the appropriate frequency band and meets the requirement of out of band emissions and unwanted emissions in the spurious domain.

11. Battery powered operation

For battery-powered operation, the module provides two sleep modes. Each mode can be entered by a specific command and left by applying a falling edge at the *WAKE-UP* pin.

This type of operation is accessible in command mode only.

	Shutdown	Standby
Enter mode	By command CMD_SHUTDOWN_REQ	By command CMD_STANDBY_REQ
Typical current consumption [μ A]	0.2	1.6
Wake-up trigger	Falling edge at the <i>WAKE-UP</i> pin	
CPU wake-up time [ms]	See chapter 9	
Wake-up behavior	The module restarts such that all volatile settings are lost.	RAM is retained and module just continues its operation.
Wake-up message	CMD_RESET_IND	CMD_STANDBY_IND

12. Custom firmware

12.1. Custom configuration of standard firmware

The configuration of the standard firmware includes adoption of the non-volatile settings to customer requirements and creating a customized product based on the standard product.

This variant will result in a customer exclusive module with a unique ordering number. It will also freeze the firmware version to a specific and customer tested version and thus results in a customer exclusive module with a unique ordering number.

Further scheduled firmware updates of the standard firmware will not be applied to this variant automatically. Applying updates or further functions require a customer request and release procedure.

12.2. Customer specific firmware

A customer specific firmware may include "Custom configuration of standard firmware" plus additional options or functions and tasks that are customer specific and not part of the standard firmware.

Further scheduled firmware updates of the standard firmware will not be applied to this variant automatically. Applying updates or further functions require a customer request and release procedure.

This also results in a customer exclusive module with a unique ordering number.

An example for this level of customization are functions like host-less operation where the module will perform data generation (e.g. by reading a SPI or I²C sensor) and cyclic transmission of this data to a data collector, while sleeping or being passive most of the time.

Also replacing UART with SPI as host communication interface is classified as a custom specific option.

Certification critical changes need to be re-evaluated by an external qualified measurement laboratory. These critical changes may occur when e.g. changing radio parameters, the channel access method, the duty-cycle or in case of various other functions and options possibly used or changed by a customer specific firmware.

12.3. Customer firmware

A customer firmware is a firmware written and tested by the customer himself or a 3rd party as a customer representative specifically for the hardware platform provided by a module.

This customer firmware (e.g. in form of an Intel hex file) will be implemented into the module's production process at our production site.

This also results in a customer exclusive module with a unique ordering number.

The additional information needed for this type of customer firmware, such as hardware specific details and details towards the development of such firmware are not available for the public and can only be made available to qualified customers.



The qualification(s) and certification(s) of the standard module cannot be applied to this customer firmware solution without a review and verification.

12.4. Contact for firmware requests

Please contact your Business Development Manager (BDM) or WCS@we-online.com for quotes regarding these topics.

13. Flooding mesh: Using the repeater functionality

The Tarvos-e can be run as a repeater to artificially extend the range of sending devices in an existing network.

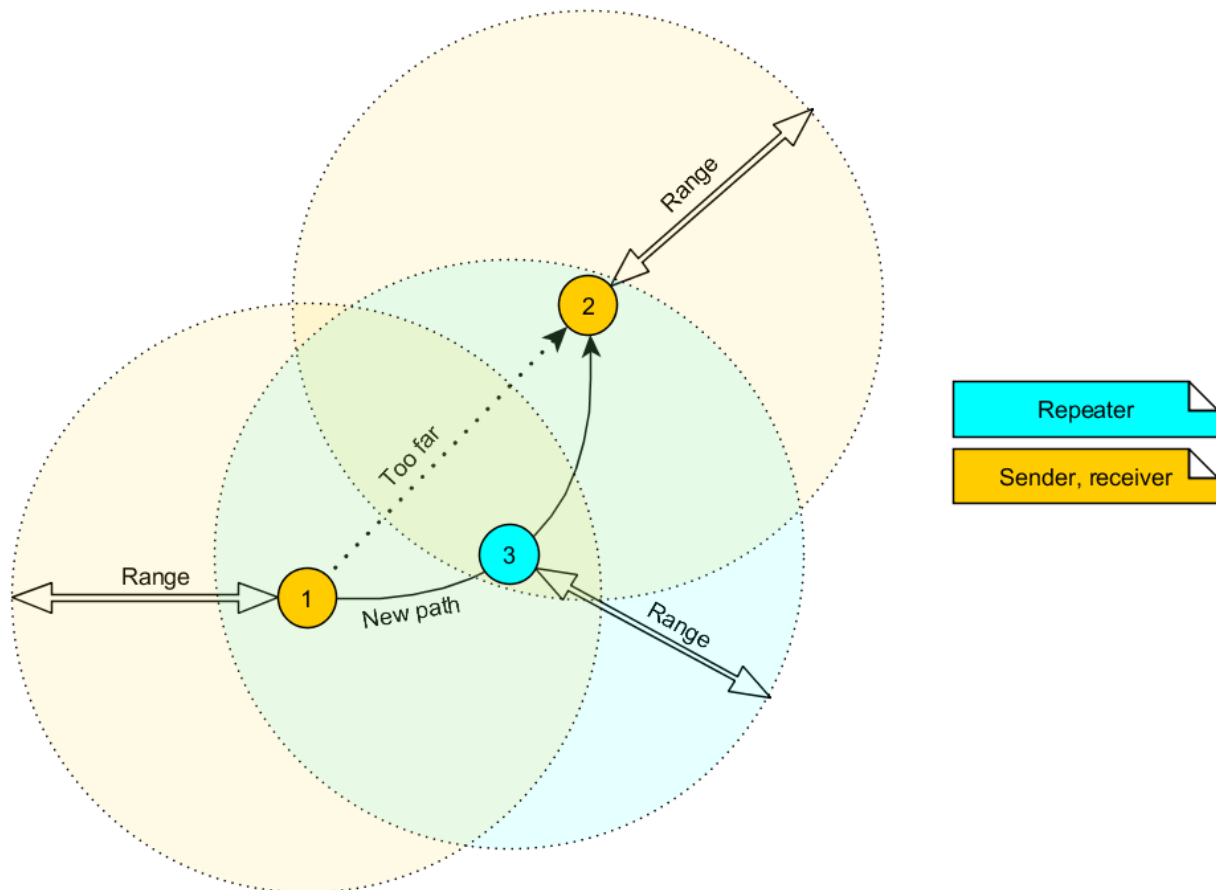


Figure 8: Range extension using several repeaters

If the module is configured as repeater, it can be simply added to existing wireless networks consisting of compatible modules. With this, the newly generated mesh network uses the so-called "flooding technique" to deliver data packets from their source to their destination device. The repeater module itself simply listens to the configured channel and forwards all received packets except the ones addressed to itself. Thereby, a random delay is used to avoid RF packet collision. To reduce traffic on the frequency channel, each repeater device checks before repetition whether it has already sent this packet or not. Thus, every repeater sends each packet only once.

In a network with **NumRP** repeater devices, each data packet is repeated **NumRP** times. Therefore, each packet that is sent from node A to node B forces a traffic of **NumRP+1** data packets in total on the frequency channel.



A module that is configured as repeater simultaneously supports the functions of a standard module. Thus, it can receive data and can initiate the data transmission to other modules.



A host connected to a radio module in repeater mode, is required to adhere to *BUSY* signal when initiating data transfers.

13.1. Setup of the network and repeater device

The repeater mode can be enabled with setting Bit 0 accordingly in the `RpFlags`.



As ACKs are not supported by the repeater mode, all network members must make sure that the user settings value of `MAC_NumRetrys` is set to 0.

If the module is configured as repeater, the following notes have to be considered:

1. Requirements on the network:

- a) The repeater devices must be line-powered (no battery), since the energy consumption is higher, due to the packet repetition.
- b) Depending on the data rate, each repeater should repeat a maximum of 2-5 packets per second, in order to increase the probability that the repeater is not busy with repeating when already a new packet arrives for repetition. Otherwise, packets can get lost. The network shall be setup such that this requirement is fulfilled. More packets per second will result in more packet loss as the collision probability will increase.
- c) If the network consists of several layers of repeaters, each layer delays the packet transmission additionally.
- d) To setup the network, all participants have to use the same `RADIO_DefaultRfProfile`, `RADIO_DefaultRfChannel` and `MAC_DefaultAddressMode`.
- e) The network must be designed by the user in such a way that the duty-cycle requirements of the local regulatory bodies cannot be exceeded.

2. Information for the repeater device:

- a) Acknowledgements (ACK) of successfully received packets are blocked. If an ACK is requested by the sending module, the request is ignored. Furthermore, the repeater does not request any ACK, when repeating a packet.
- b) The "packet sniffer" mode cannot run at the same time as the module is in repeater mode.

- c) Each time a packet has been repeated a `CMD_REPEAT_IND` is output over UART. Depending on the address mode, the address of the involved devices is placed in the `CMD_REPEAT_IND` telegram. With this, the original sender of the RF packet and the device, that is supposed to receive the packet, can be identified.
3. Information for the sending and receiving devices:
- a) The senders should send less frequently to avoid packet collision on the frequency channel and to not exceed the duty cycle requirements.
 - b) The repeater devices do not support the feature of ACKs for the successful reception of the packets. Thus, the sender will never receive ACKs if requested. To ensure that transmitted packets are successfully received by the destination device, the network administrator has to integrate his own acknowledging feature in the customer's application. To be sure that the sender does not request ACKs the user setting `MAC_NumRetrys` must be set to 0.
 - c) Every repeater sends each packet only once. However, receivers can receive each packet several times (sent by different repeaters), if there are packets of different content in the network temporally close to each other. Thus, on the side of the receiving device, a mechanism that detects and filters double packets shall be implemented.

13.2. Example network

In the example network shown below, the goal is to send a packet from device 1 to 5. Without the repeater devices, this would be impossible. The steps are as follows:

1. Sender 1 sends a packet.
 - a) Repeater 2 and 3 receive and accept it at the same time.
2. Device 2 and 3 delay the packet.
 - a) Repeater 3 sends the packet.
 - i. Sender 1 and 6 do not accept it, since their addresses are wrong (unequal 5).
 - ii. Repeater 2 does not accept it, since it has been already received before.
 - b) Repeater 2 sends the packet.
 - i. Repeaters 3 does not accept it, since it has been already received before.
 - ii. Sender 1 does not accept it, since its address is wrong (unequal 5).
 - iii. Repeater 4 receives and accepts the packet.
3. Repeater 4 delays and sends the packet.
 - a) Sender 6 and 7 do not accept it, since their addresses are wrong (unequal 5).
 - b) Repeater 2 does not accept it, since it has been already received before.
 - c) Receiver 5 accepts it and its successfully delivered (address equals 5).

Note that the packet forwarded by repeater 2 and 3 would collide in the frequency channel, if they wouldn't be randomly delayed (see `RP_NumSlots`).

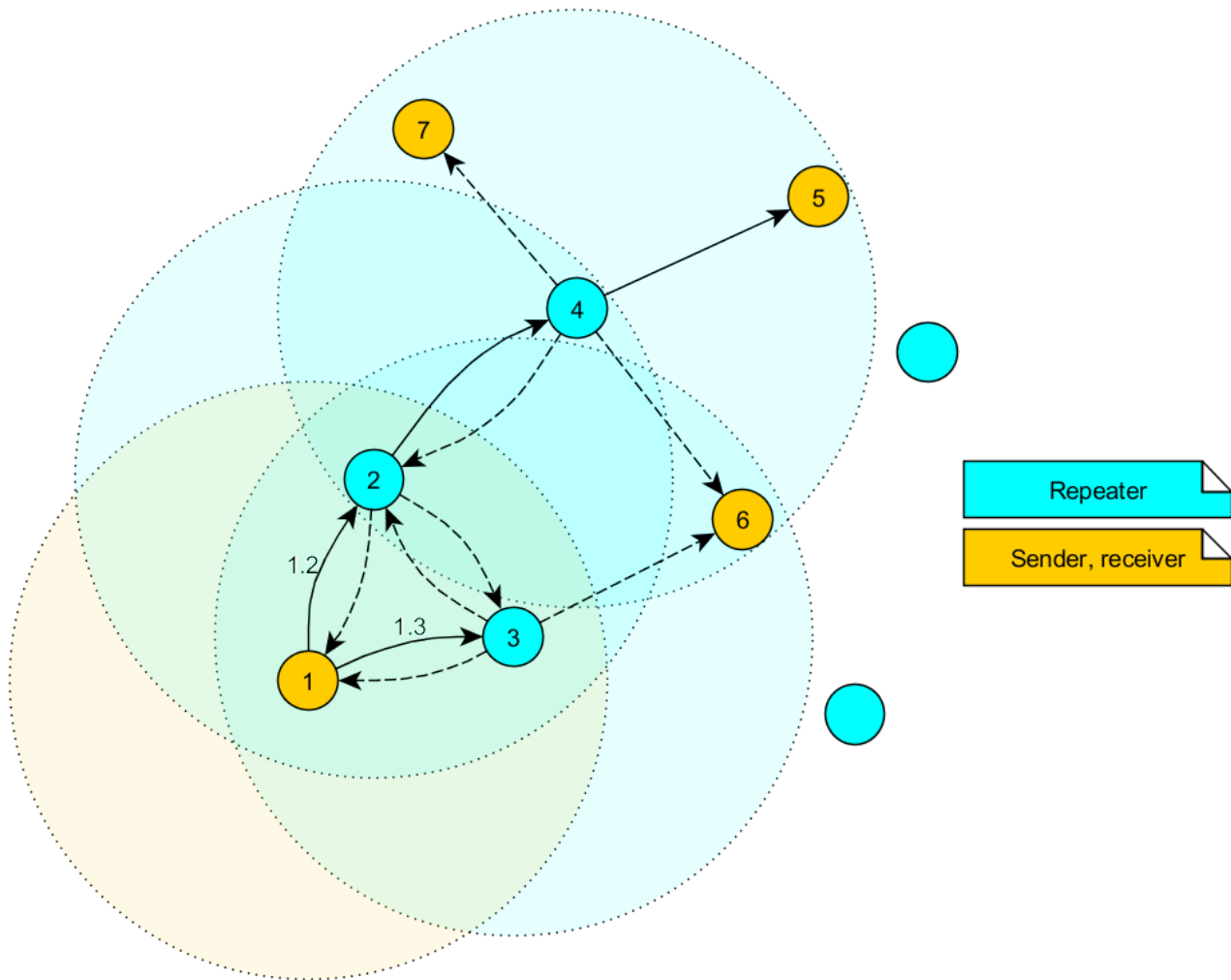


Figure 9: Example network

13.2.1. Application in parallel networks

As described above, a repeater device forwards all packets that are received. If a network needs to have a bigger throughput of data, a parallel network can be set up, that relaxes the stress of the primary network. To do so, all sending, receiving and repeater devices of the parallel network are configured to use a new non-overlapping channel, such that the primary network is not affected at all by the traffic of the parallel network. All nodes in the networks shall not be closer to each other than 2 meters. In case it cannot be avoided the TX power parameter of devices close to each other must be reduced.

14. Listen Before Talk (LBT)

This section describes the Listen Before Talk (LBT) feature. A radio transmitter performing an LBT, assesses the channel and proceeds with transmission only when the channel is free. This method provides a way for collision avoidance at the cost of latency and throughput.

This function is disabled by default in the Tarvos-e module meaning that the module transmits the data without checking if the channel is free.

If LBT is enabled, the module uses a channel access scheme called CSMA-CA (Carrier Sense Multiple Access with Collision Avoidance). The transmitter performs a signal strength measurement on the configured channel. If the measured signal strength is below a certain threshold, the channel is considered to be free and the packet is transmitted. In case the signal strength detected is beyond a certain threshold, the channel is considered to be busy. In this case, the host gets a channel busy status indicated.

To enable and configure this feature, two user settings are used. First of all `LBT_ObservationPeriod`, which is used to enable or disable the feature, where '0' means feature is disabled and any other value enables the feature and specifies for how long to observe the chosen channel.

In addition to this, a threshold `LBT_Threshold` can be configured, which is used for deciding either "channel is free" or "channel is busy".

In the figure 10 below, the procedure to determine if the channel is busy or free depending on the values of the parameters is shown.

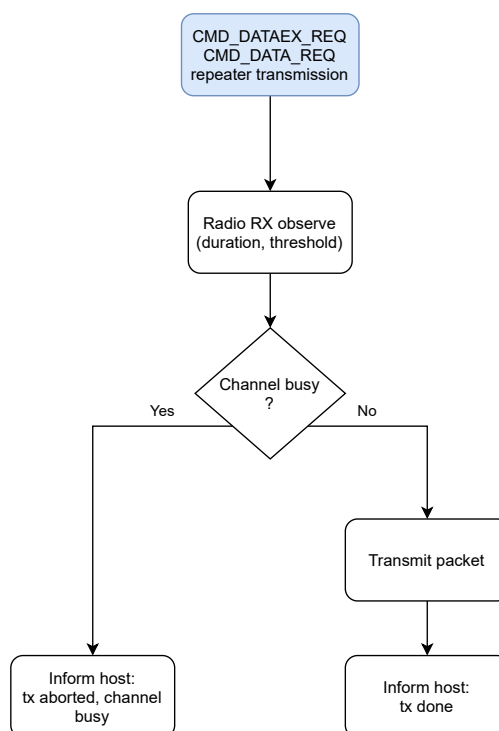


Figure 10: Listen Before Talk

15. Using the long range mode

The module provides several so called LRM ("long range modes") that allow to achieve ranges of up to 3 km with matching antenna above ground levels at the cost of net data rate, throughput and packet duration. To enable any long range mode, the parameter `RADIO_DefaultRfProfile` must be set to the corresponding long range profile 4. To do so, the `CMD_SET_REQ` can be used as it is in case of any other parameter. In this particular case, it looks as follows:

Start signal	Command	Length	Settings index	Parameter	CS
0x02	0x09	0x02	0x01	0x04	0x0C

Response `CMD_SET_CNF`: Successfully modified the setting.

Start signal	Command 0x40	Length	Status	CS
0x02	0x49	0x01	0x00	0x4A

16. Compatibility to existing proprietary modules

Under certain conditions and settings, the Tarvos-e is radio and/or command compatible to Tarvos-II and Tarvos-I and their related USB dongles. To allow interoperability check the following settings:

General: Tarvos-II firmware must be of version 3.5.0 or later, Tarvos-I firmware must be 2.1.0 or later

RF profiles / RF settings: RF-profile 0 (38.4 kBaud) and RF-profile 2 (100 kBaud) are compatible to existing modules. The remaining profiles are for Tarvos-e usage only.

Address mode: Tarvos-I supports address mode 0 and 1. The Tarvos-II additionally supports address mode 2.

Addresses: `MAC_DefaultDestAddr` and `MAC_DefaultDestNetID` are set to the corresponding broadcast addresses (255 and/or 65535), so a `CMD_DATA_REQ` after a reset in any `MAC_DefaultAddressMode` will result in a Broadcast frame. The "old" modules have selected 0 as default destination address and NetID.

User data size: Tarvos-I supports up to 120 Bytes user data. Tarvos-II supports up to 128 Bytes payload.

Timings: Some timings of existing modules (ACK timeouts with retries) may need adjustment (i.e. increased timeouts).

Pinout: The pinout for basic functionality is kept the same as Tarvos-I and Tarvos-II. Thus, `UART_RX`, `UART_TX` and `RTS`, `/RESET`, `GND`, `VCC` and `LED`'s remain on the same pads. Nevertheless, the Tarvos-e requires further pins to operate: those pins are `BOOT` and `WAKE-UP`. Also the electrical characteristics over all hardware platforms are not identical.

Operation mode: The Tarvos-e supports command mode using the same command structure as known from previous products but with slightly changed commands (e.g. `CMD_SET_REQ` and `CMD_GET_REQ` structures were changed for better usability). The transparent mode is not available on Tarvos-e with Firmware Version < 3.0.0 and the default mode of operation is command mode.

UART: The Tarvos-e uses 115200 Baud 8n1 instead of 9600 Baud 8n1 as factory default for the UART. Users can change this setting to 9600 Baud using the `CMD_SET_REQ` command.

Low power mode: Tarvos-e will enable low power modes on UART commands `CMD_STANDBY_REQ` and `CMD_SHUTDOWN_REQ`. In low power mode, the UART is disabled and a `WAKE-UP` can be triggered by using the `WAKE-UP` pin accordingly.

16.1. Restrictions

Tarvos-II: To successfully transmit ACKs from an Tarvos-e to Tarvos-II the parameter `MAC_AckTimeout` of the Tarvos-II must be set to a value of at least 20 ms. Furthermore, the firmware of the Tarvos-II must be of version 3.5.0 or newer.

Tarvos-I, Tarvos: To successfully transmit ACKs from Tarvos-e to Tarvos-I the parameter `MAC_AckTimeout` of the Tarvos-I must be set to a value of at least 20 ms. Furthermore, the firmware of the Tarvos-I must be of version 2.1.0 or newer.

16.2. Tarvos-III and Tarvos-e

Tarvos-III and Tarvos-e share the same firmware base and are compatible except:

- Radio RF Profile 3, this profile is not supported with Tarvos-e
- Hardware platform related parts of the Firmware are different (pin mapping).

17. Firmware updates

All products will experience maintenance, security and/or feature updates from time to time. For the standard products, these are maintained via the PCN process (according to JEDEC standard J-STD-046).

Customers can request the creation of a customized product including a "firmware freeze" to ensure that they will receive their verified product, even if the standard product is updated.



Implementers shall implement the firmware update possibility here to be used in their end application.

17.1. Firmware flashing using the production interface

Most Würth Elektronik eiSos wireless connectivity modules offer a production interface (e.g. JTAG, SWD, Spy-Bi-Wire) for module flash access. Depending on the product, this interface can be used by customers to erase the entire chip and install their own firmware.

Using the production interface is not intended to perform updates of Würth Elektronik eiSos standard product firmware.

Production firmware images and binary files for Würth Elektronik eiSos wireless connectivity modules are not publicly available.



Any certification, declaration, listing and qualification becomes invalid if the production interface is used by a customer. Some products, in their documentation, state exceptions to this invalidation under certain conditions.

Customers shall make the product specific firmware update interface available to their application. These methods will use a wired (UART, SPI, etc.) or wireless (Bluetooth® LE, WiFi, etc.) communication interface of the module to allow updating the product's firmware. Details are described in the next section.

17.2. Update via ACC software and UART

Only the *BOOT*, *UTDX*, *URXD* and *GND* signals are needed for this connection. A suitable adapter/converter is required for a PC connection (e.g. the FTDI TTL-323R-3V3 UART to USB converter).

The pin *BOOT* must be on high level (during and shortly after a reset) in order to start the bootloader (details see chapter *Quickstart*). The reset signal shall be connectable to GND for performing a reset of the module (e.g. using a push-button which pulls to *GND* when pressed). The */RESET* pin has an internal pull-up of 100 kΩ.



None of the module pins are 5 V TTL compatible. Applying over-voltage to any pin, may damage the hardware permanently. Voltage levels in the range of the electrical specification must be assured, as shown in chapter 2



Users must make sure that their host is not accessing the Tarvos-e RX line (i.e. pulling it HIGH or LOW) as that will prevent ACC to access the module.

As long as our standard firmware is running on the module, it can be updated with the PC utility "ACC" via the serial interface. If the module is not directly connected to a PC, then at least the UART should be made accessible, e.g. by means of a suitable connector.

18. Firmware history

Version 3.3.0 "Release"

- Version 3.3.0 is the first release of Tarvos-e the version number is kept so the compatibility towards Tarvos-III is visible in terms of firmware version.
- Improve stability of the radio and repeater function under stress.
- The on-time of the pins *TX_IND* and *RX_IND* has been adjusted. They show the accurate time of transmitting/receiving a radio packet now.
- Added Listen Before Talk (LBT) feature. The module will check whether the radio channel is free before starting the data transmission, if this feature is enabled. Default: disabled.
- Added a new busy status for *CMD_DATA_CNF* that is returned when the module is busy (e.g. due to radio channel busy) and it receives either *CMD_DATA_REQ* or *CMD_DATAEX_REQ*.
- Double Packet detection algorithm was adopted. It now only contains 1 frame in case of AddressMode 0. All other AddressMode (1,2 and 3) compare the 9 most recent frame headers for the double packet status.
- Updated random function is applied system wide (e.g. selecting the TX slot for repeated radio frames, radio sequence number)

18.1. Known issues

Firmware version 3.3.0 is the first release of Tarvos-e the FW version number is kept so the compatibility towards Tarvos-III is visible in terms of firmware version. For the sake of completeness the known issues are kept in sync with Tarvos-III as well even if due to the lowest available version being 3.3.0 some of them do not apply to Tarvos-e.

ID	Details	Affected versions
KI-001	Description: TI-RTOS: Additional latencies up to 5 ms due to task priorities may occur. Affected functions: System timings. Workaround: None	All
KI-002	Description: Temperature compensation of radio profile 3 not suitable for HW-Version 2.2 or older. Affected functions: Radio profile 3. Workaround: None	$\leq 2.1.0$

KI-003	Description: In scenarios with high radio traffic the device may not enter the standby mode properly, if the command CMD_STANDBY_REQ has been placed. In case of misbehaviour the current consumption does not meet the specification. Affected functions: Command CMD_STANDBY_REQ. Workaround: None	$\leq 2.1.0$
KI-004	Description: In case a CMD_DATAEX_REQ is used with a wrong channel number, the module answers with a CMD_DATAEX_CNF (0x02 0x41 0x01 0x02 0x40) instead of a CMD_DATA_CNF (0x02 0x40 0x01 0x02 0x41) message. Affected functions: Command CMD_DATAEX_REQ. Workaround: None	$\leq 2.4.0$
KI-005	Description: In case of data transmission with ACK enabled, the commands CMD_DATA_REQ and CMD_DATAEX_REQ may not respond with a CMD_DATA_CNF, if a bit error occurs in the ACK (receiver is located at the range limit or poor radio link). Affected functions: Commands CMD_DATA_REQ and CMD_DATAEX_REQ. Workaround: In case the module does not respond with a CMD_DATA_CNF within a timeout (depending on the data rate and number of retries configured), reset the radio module and continue with the application.	$\leq 2.5.0$
KI-006	Description: When switching from Command into Transparent Mode using the CMD_SET_MODE_REQ the <i>RTS</i> will stay high till the first byte is received in transparent mode. Affected functions: Command CMD_SET_MODE_REQ and flow control function. Workaround: Use one of the other methods to enter transparent mode or ignore <i>RTS</i> state for first byte.	3.0.0

KI-007	Description: When the repeater is enabled and the module is under stress the module gets stuck in a state where it stops receiving new packets. Affected functions: Receiving packets. Workaround: Send a packet using the commands CMD_DATA_REQ or CMD_DATAEX_REQ to cause the module to start receiving again after a packet has been transmitted.	≤ 3.0.0
KI-008	Description: An engineering firmware image was provided to selected customer under version tag 3.3.0 for update via ACC. However this firmware will not be the final released firmware 3.3.0. Affected functions: Random function and Double Packet filtering. Workaround: Delete all firmware images for 3.3.0 and re-download them from the ACC server after PCN active date.	3.3.0 (Engineering)

19. Hardware history

Version 2.2 "Release Version"

- Design Freeze in June 2024
- Released in July 2024 after completed CE measurements.

20. Design in guide

20.1. Advice for schematic and layout

For users with less RF experience it is advisable to closely copy the relating EV-Board with respect to schematic and layout, as it is a proven design. The layout should be conducted with particular care, because even small deficiencies could affect the radio performance and its range or even the conformity.

The following general advice should be taken into consideration:

- A clean, stable power supply is strongly recommended. Interference, especially oscillation can severely restrain range and conformity.
- Variations in voltage level should be avoided.
- LDOs, properly designed in, usually deliver a proper regulated voltage.
- Blocking capacitors and a ferrite bead in the power supply line can be included to filter and smoothen the supply voltage when necessary.



No fixed values can be recommended, as these depend on the circumstances of the application (main power source, interferences etc.).



The use of an external reset IC should be considered if one of the following points is relevant:



- The slew rate of the power supply exceeds the electrical specifications.
- The effect of different current consumptions on the voltage level of batteries or voltage regulators should be considered. The module draws higher currents in certain scenarios like start-up or radio transmit which may lead to a voltage drop on the supply. A restart under such circumstances should be prevented by ensuring that the supply voltage does not drop below the minimum specifications.
- Voltage levels below the minimum recommended voltage level may lead to malfunction. The reset pin of the module shall be held on LOW logic level whenever the VDD is not stable or below the minimum operating Voltage.
- Special care must be taken in case of battery powered systems.

- Elements for ESD protection should be placed on all pins that are accessible from the outside and should be placed close to the accessible area. For example, the RF-pin is accessible when using an external antenna and should be protected.
- ESD protection for the antenna connection must be chosen such as to have a minimum effect on the RF signal. For example, a protection diode with low capacitance such as the 8231606A or a 68 nH air-core coil connecting the RF-line to ground give good results.
- Placeholders for optional antenna matching or additional filtering are recommended.
- The antenna path should be kept as short as possible.



Again, no fixed values can be recommended, as they depend on the influencing circumstances of the application (antenna, interferences etc.).

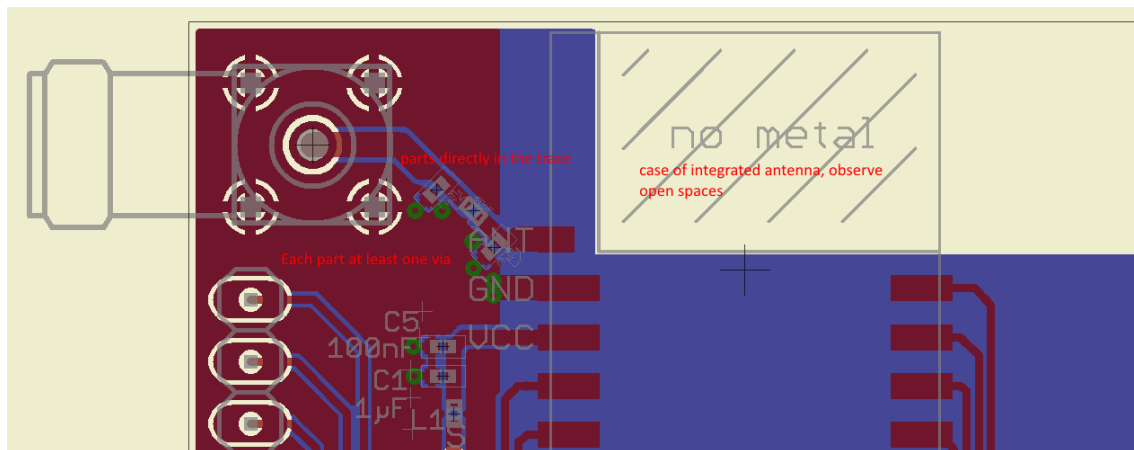


Figure 11: Layout

- To avoid the risk of short circuits and interference there should be no routing underneath the module on the top layer of the baseboard.
- On the second layer, a ground plane is recommended, to provide good grounding and shielding to any following layers and application environment.
- In case of integrated antennas it is required to have areas free from ground. This area should be copied from the EV-Board.
- The area with the integrated antenna must overlap with the carrier board and should not protrude, as it is matched to sitting directly on top of a PCB.
- Modules with integrated antennas should be placed with the antenna at the edge of the main board. It should not be placed in the middle of the main board or far away from the edge. This is to avoid tracks beside the antenna.

- Filter and blocking capacitors should be placed directly in the tracks without stubs, to achieve the best effect.
- Antenna matching elements should be placed close to the antenna / connector, blocking capacitors close to the module.
- Ground connections for the module and the capacitors should be kept as short as possible and with at least one separate through hole connection to the ground layer.
- ESD protection elements should be placed as close as possible to the exposed areas.

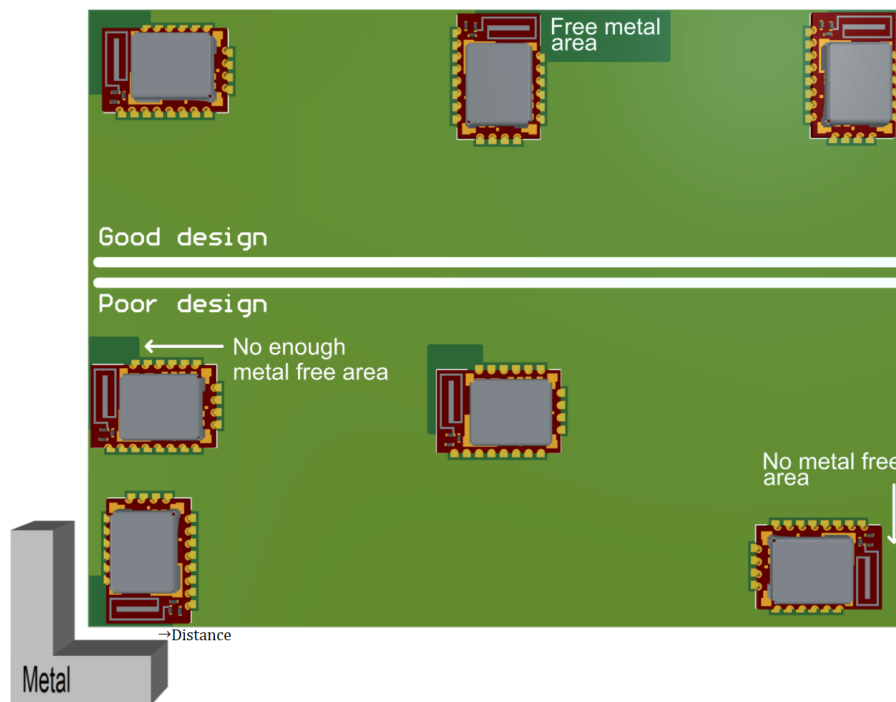


Figure 12: Placement of the module with integrated antenna

20.2. Designing the antenna connection

The antenna should be connected with a $50\ \Omega$ line. This is needed to obtain impedance matching to the module and avoids reflections. Here we show as an example how to calculate the dimensions of a $50\ \Omega$ line in form of a micro strip above ground, as this is easiest to calculate. Other connections like coplanar or strip line are more complicated to calculate but can offer more robustness to EMC. There are free calculation tools available in the internet.

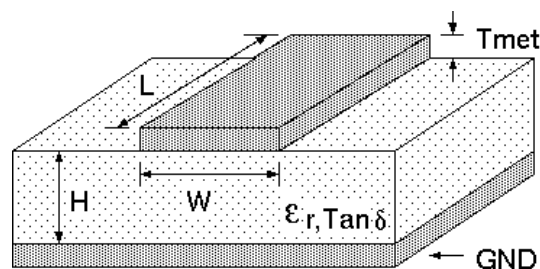


Figure 13: Dimensioning the antenna connection as micro strip

The width W for a micro strip can be calculated using the following equation:

$$W = 1.25 \times \left(\frac{5.98 \times H}{e^{\frac{50 \times \sqrt{\epsilon_r + 1.41}}{87}}} - T_{met} \right) \quad (4)$$

Example:

A FR4 material with $\epsilon_r = 4.3$, a height $H = 1000 \mu\text{m}$ and a copper thickness of $T_{met} = 18 \mu\text{m}$ will lead to a trace width of $W \sim 1.9 \text{ mm}$. To ease the calculation of the micro strip line (or e.g. a coplanar) many calculators can be found in the internet.

- As rule of thumb a distance of about $3 \times W$ should be observed between the micro strip and other traces / ground.
- The micro strip refers to ground, therefore there has to be the ground plane underneath the trace.
- Keep the feeding line as short as possible.

20.3. Antenna solutions

There exist several kinds of antennas, which are optimized for different needs. Chip antennas are optimized for minimal size requirements but at the expense of range, PCB antennas are optimized for minimal costs, and are generally a compromise between size and range. Both usually fit inside a housing.

Range optimization in general is at the expense of space. Antennas that are bigger in size, so that they would probably not fit in a small housing, are usually equipped with a RF connector. A benefit of this connector may be to use it to lead the RF signal through a metal plate (e.g. metal housing, cabinet).

As a rule of thumb a minimum distance of $\lambda / 10$ (which is 3.5 cm @ 868 MHz and 1.2 cm @ 2.44 GHz) from the antenna to any other metal should be kept. Metal placed further away will not directly influence the behavior of the antenna, but will anyway produce shadowing.



Keep the antenna as far as possible from large metal objects to avoid electro-magnetic field blocking.

In the following chapters, some special types of antenna are described.

20.3.1. Wire antenna

An effective antenna is a $\lambda/4$ radiator with a suiting ground plane. The simplest realization is a piece of wire. It's length is depending on the used radio frequency, so for example 8.6 cm 868.0 MHz and 3.1 cm for 2.440 GHz as frequency. This radiator needs a ground plane at its feeding point. Ideally, it is placed vertically in the middle of the ground plane. As this is often not possible because of space requirements, a suitable compromise is to bend the wire away from the PCB respective to the ground plane. The $\lambda/4$ radiator has approximately 40 Ω input impedance. Therefore, matching is not required.

20.3.2. Chip antenna

There are many chip antennas from various manufacturers. The benefit of a chip antenna is obviously the minimal space required and reasonable costs. However, this is often at the expense of range. For the chip antennas, reference designs should be followed as closely as possible, because only in this constellation can the stated performance be achieved.

20.3.3. PCB antenna

PCB antenna designs can be very different. The special attention can be on the miniaturization or on the performance. The benefits of the PCB antenna are their small / not existing (if PCB space is available) costs, however the EV of a PCB antenna holds more risk of failure than the use of a finished antenna. Most PCB antenna designs are a compromise of range and space between chip antennas and connector antennas.

20.3.4. Antennas provided by Würth Elektronik eiSos

Besides the radio modules Würth Elektronik eiSos provides various antennas tailored for the different frequency bands. The recommended single external antennas are shown in the subsequent chapters.



In case integrated multilayer chip antennas are needed because of space limitations, please refer to
<https://www.we-online.com/en/components/products/WE-MCA>.

20.3.4.1. 2600130086 - Hermippe-III dipole antenna

Well suited for applications where the RF is lead through a metal wall that could serve as ground plane to the antenna.



Figure 14: Hermippe-III dipole antenna

Specification	Value
Frequency range [MHz]	855 – 915
VSWR (free space, without ground plane)	≤ 2.0
Polarisation	Linear
Impedance [Ω]	50 ± 5
Connector	SMA (Male)
Dimensions (L x d) [mm]	$50 \pm 3 \times 7.92 \pm 0.2$
Weight [g]	4.5
Operating temp. [$^{\circ}\text{C}$]	-40 – +85

20.3.4.2. 2600130081 - Hyperion-I dipole antenna



Figure 15: Hyperion-I dipole antenna

Ideally suited for applications where no ground plane is available.

Specification	Value
Center frequency [MHz]	868
Frequency range [MHz]	853 – 883
Wavelength	$\lambda / 2$
VSWR	≤ 2.0
Impedance [Ω]	50
Connector	SMA (Male)
Dimensions (L x d) [mm]	142 x 10
Peak gain [dBi]	-2.3
Operating temp. [$^{\circ}\text{C}$]	-30 – +80

20.3.4.3. 2600130082 - Hyperion-II magnetic base antenna

Well suited for applications where the RF is lead through a metal wall that could serve as ground plane to the antenna.



Figure 16: Hyperion-II magnetic base antenna with 1.5 m antenna cable



The 2600130082 is an antenna in form of $\lambda/4$ and therefore needs a ground plane at the feeding point.

Specification	Value
Frequency range [MHz]	824 – 894
VSWR	≤ 2.0
Polarisation	Vertical
Impedance [Ω]	50 ± 5
Connector	SMA (Male)
Dimensions (L x d) [mm]	89.8 x 27
Weight [g]	50 ± 5
Operating temp. [$^{\circ}\text{C}$]	-30 – +60

21. Reference design

21.1. Receiver Sensitivity

The module reacts with reduced receiver sensitivity if coupling between radio and Pin 4, Test2 occurs. The following points can be used to suppress this coupling:

- 68 pF capacitor on Pin4.
- 4-Layer PCB with Signal/GND - GND - Power/GND - Signal/GND layer and routing.
- Ground in between the signal lines properly connected to GND plane.

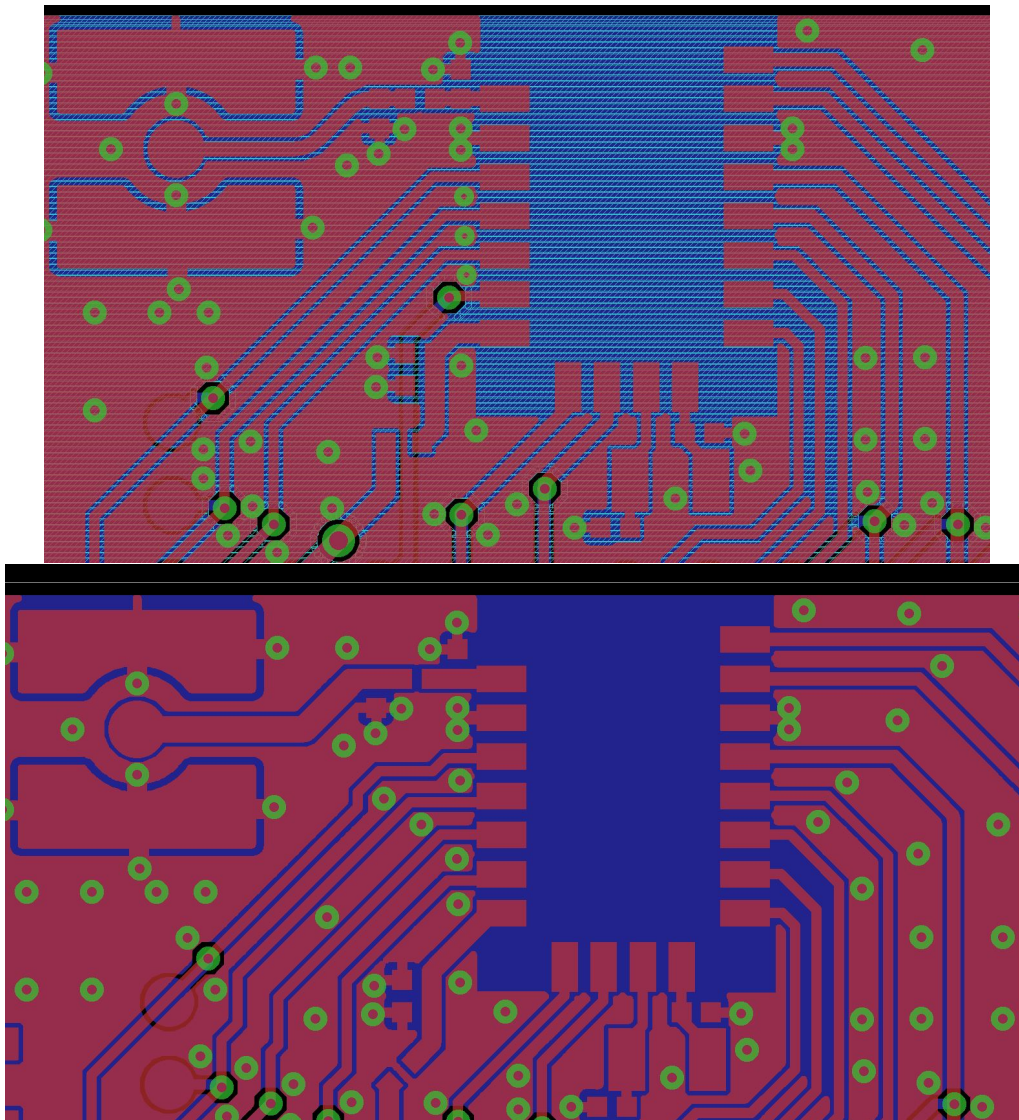


Figure 17: Examples for good decoupling

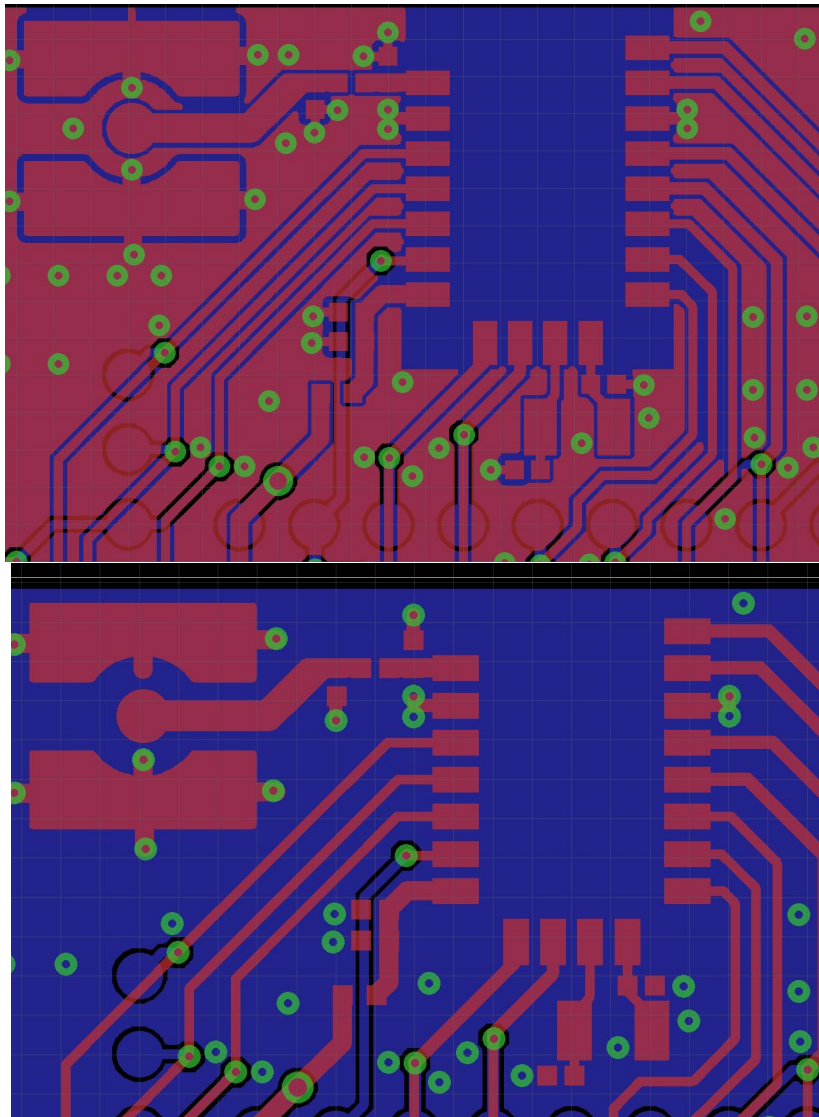


Figure 18: Examples for poor decoupling

21.2. EMC immunity behavior

For a radio device following the "Radio Equipment Directive", the multi-part EMC standard EN 301 489 is applicable, referencing the EMC basic standards of the EN 6100-* series.

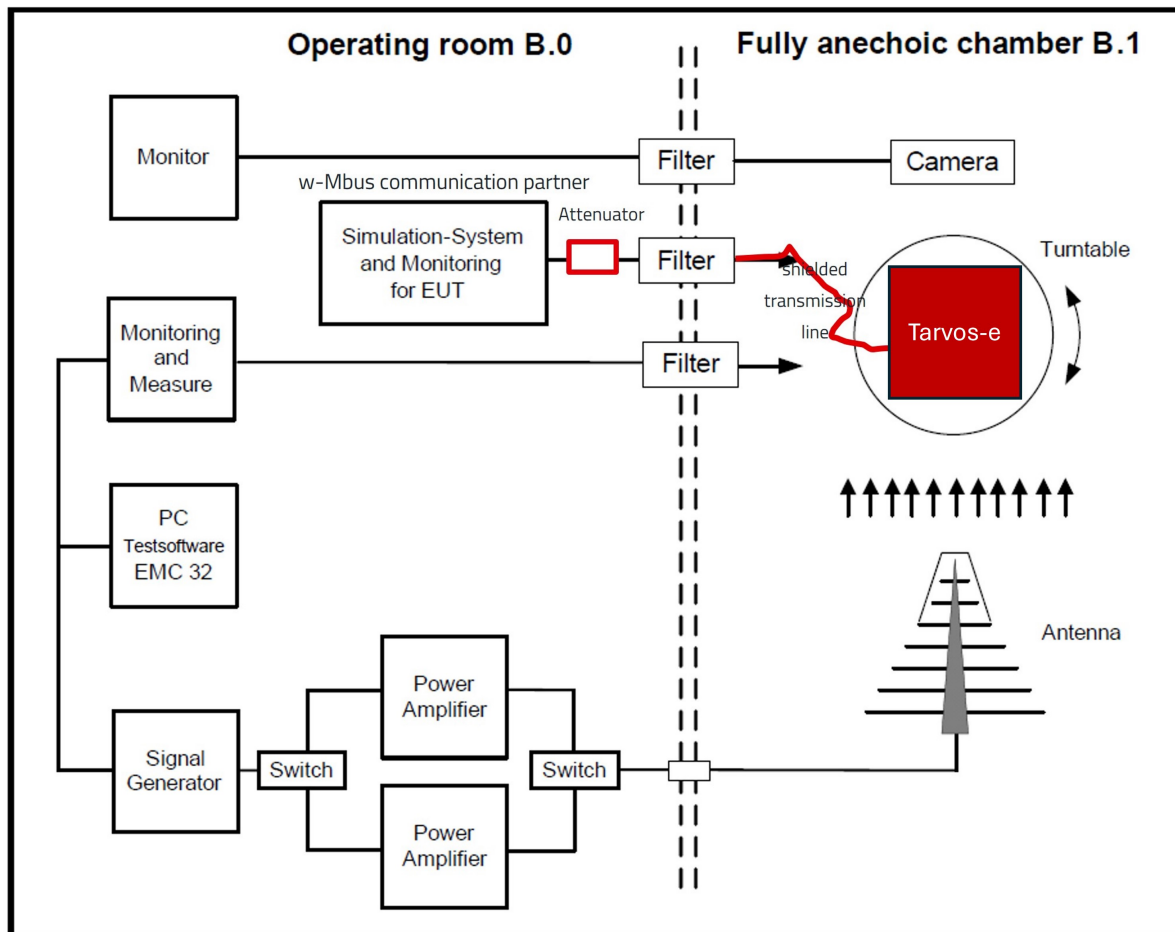
Part of the EMC test is the radio immunity. The goal of this test is to verify the device's proper functioning within a radio frequency electromagnetic field, which could be present in any environment.

Everything connected to PIN1 of Tarvos-e itself is within the scope of the test for the spectrum aspects. In case of Tarvos-e, an 868 MHz product, the EN 300 220 is applied for the spectrum aspects.

Therefore the EMC test for the Tarvos-e, as a stand alone radio module, and according to standard EN 301 489, shall include everything but exclude these spectrum aspects.

In the standard this is described in the specification of the arrangements of test signals:

"For transmitters with an antenna connector, the wanted RF output signal to establish a communication link shall be delivered from the antenna connector to the monitoring equipment (AE) by a shielded transmission line, such as a coaxial cable."



As the Tarvos-e has no integrated antenna but a connector, the compliance test were performed this way.

Furthermore, tests that are not mandatory have been performed including an attached antenna. Depending on the antenna and its ability to absorb energy of specific frequencies of the RF electromagnetic field, the RSSI value is influenced and loss of packets can occur. The phenomenon of lost packets is observed with both tested antennas, the Hermippe-III and Hyperion-I.

This means that special care has to be taken and if:

- The antenna is integrated and the communication link is not delivered by a shielded transmission line.
- The loss of packets is critical.
- The device is used in an environment where EMC disturbances are most likely present.

The evaluation board includes the reference design for an optional filter path. Using narrow band SAW filters eliminates this phenomenon completely. Tests might be needed to decide whether, filtering is needed or not, as the behavior on an antenna outside the used frequency range is usually not specified.

Table 16 give guidance about the implementation depending on the ability of the antenna to absorb energy of the specific frequencies of the RF electromagnetic field, the requirements on packet errors and the probability of EMC disturbance.

Application and environmental conditions	Integrated narrow band antenna	Integrated wide band antenna	Radio connector
Packet loss uncritical (PER < 10 %) Or High risk of EMC disturbance	SAW filter small likely needed	SAW filter likely needed	SAW filter small likely needed Hermippe-III suitable
Packet loss critical (PER > 10 %) Or Low risk of EMC disturbance	SAW filter unlikely needed	SAW filter small likely needed	SAW filter unlikely needed Hermippe-III or Hyperion-I suitable

Table 16: Implementation



For the EMC test the acceptable PER (packet error rate) for the end device has to be defined.

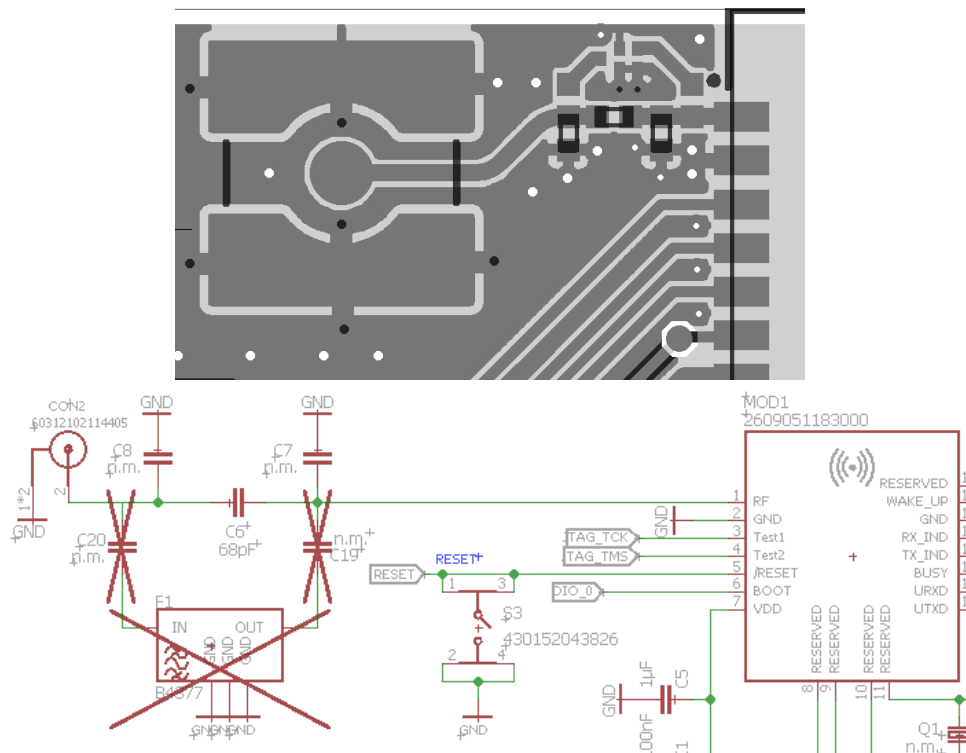


Figure 19: Example without filter

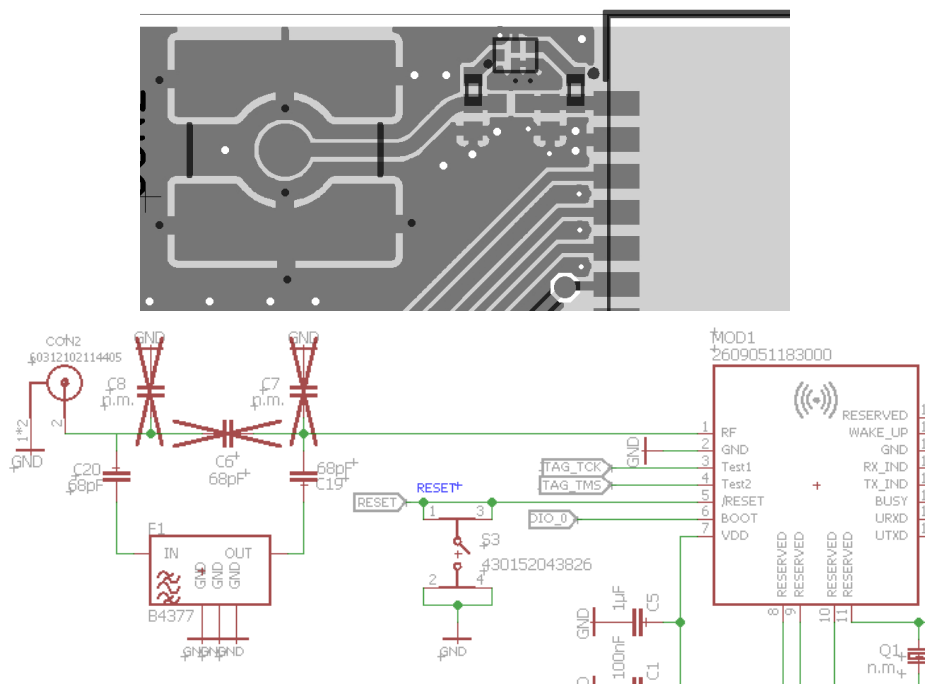
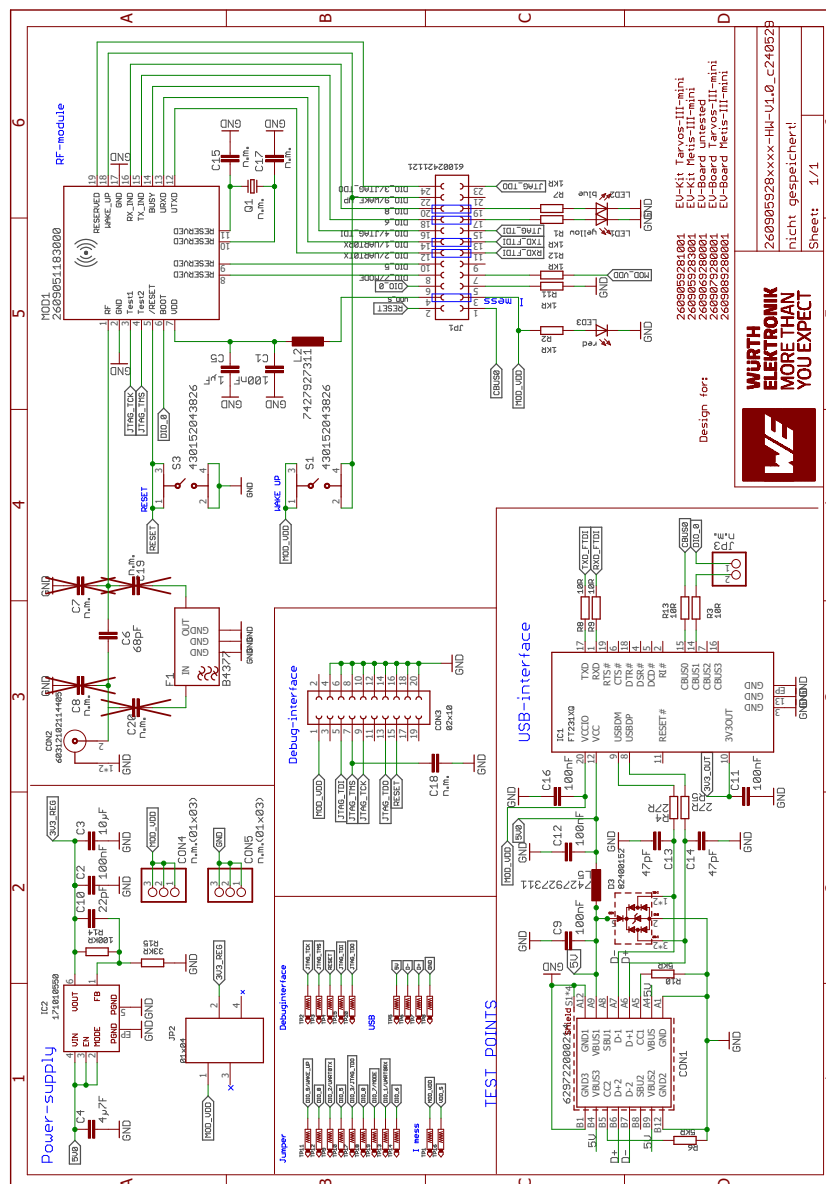


Figure 20: Example with filter



21.4. Layout

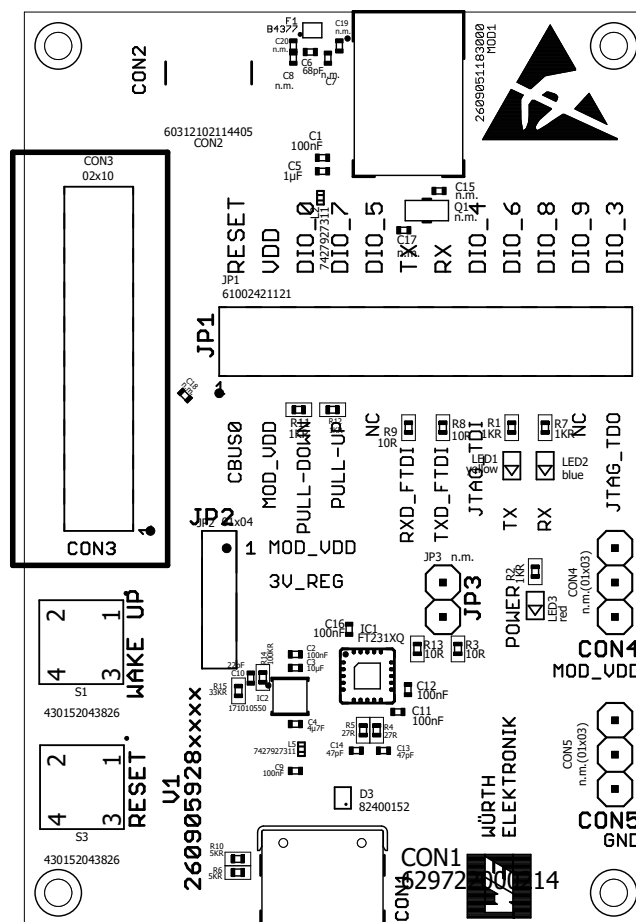


Figure 21: Assembly and silk screen diagram

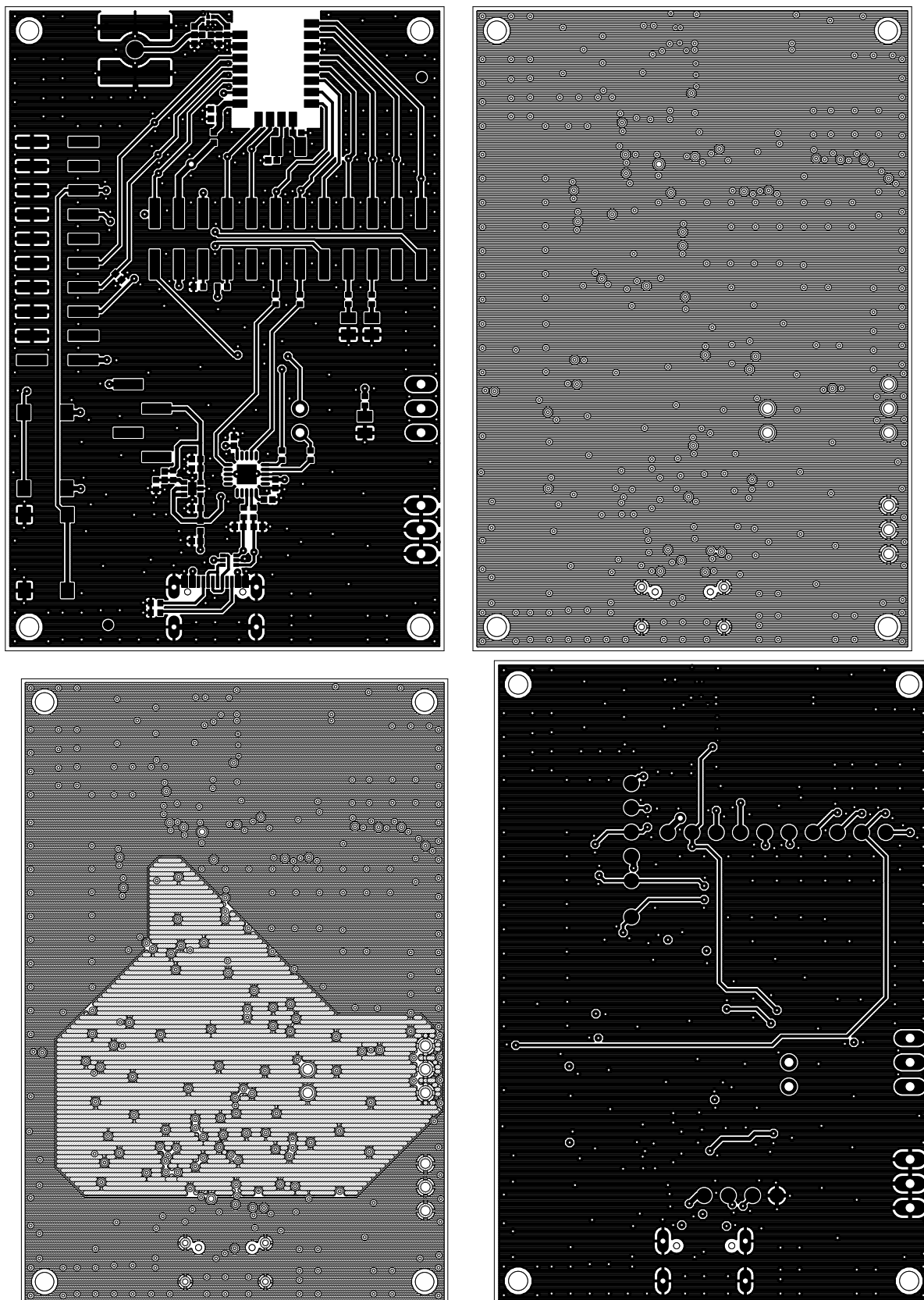


Figure 22: Top and Bottom Layer

22. Manufacturing information

22.1. Moisture sensitivity level

This wireless connectivity product is categorized as JEDEC Moisture Sensitivity Level 3 (MSL3), which requires special handling.

More information regarding the MSL requirements can be found in the IPC/JEDEC J-STD-020 standard on www.jedec.org.

More information about the handling, picking, shipping and the usage of moisture/reflow and/or process sensitive products can be found in the IPC/JEDEC J-STD-033 standard on www.jedec.org.

22.2. Soldering

22.2.1. Reflow soldering

Attention must be paid on the thickness of the solder resist between the host PCB top side and the modules bottom side. Only lead-free assembly is recommended according to JEDEC J-STD020.

Profile feature		Value
Preheat temperature Min	$T_{S \text{ Min}}$	150 °C
Preheat temperature Max	$T_{S \text{ Max}}$	200 °C
Preheat time from $T_{S \text{ Min}}$ to $T_{S \text{ Max}}$	t_S	60 - 120 seconds
Ramp-up rate (T_L to T_P)		3 °C / second max.
Liquidous temperature	T_L	217 °C
Time t_L maintained above T_L	t_L	60 - 150 seconds
Peak package body temperature	T_P	245 °C
Time within 5 °C of actual peak temperature	t_P	20 - 30 seconds
Ramp-down Rate (T_P to T_L)		6 °C / second max.
Time 20 °C to T_P		8 minutes max.

Table 17: Classification reflow soldering profile, Note: refer to IPC/JEDEC J-STD-020E

It is recommended to solder this module on the last reflow cycle of the PCB. For solder paste use a LFM-48W or Indium based SAC 305 alloy (Sn 96.5 / Ag 3.0 / Cu 0.5 / Indium 8.9HF / Type 3 / 89%) type 3 or higher.

The reflow profile must be adjusted based on the thermal mass of the entire populated PCB, heat transfer efficiency of the reflow oven and the specific type of solder paste used. Based on the specific process and PCB layout the optimal soldering profile must be adjusted and verified. Other soldering methods (e.g. vapor phase) have not been verified and have to be validated

by the customer at their own risk. Rework is not recommended.

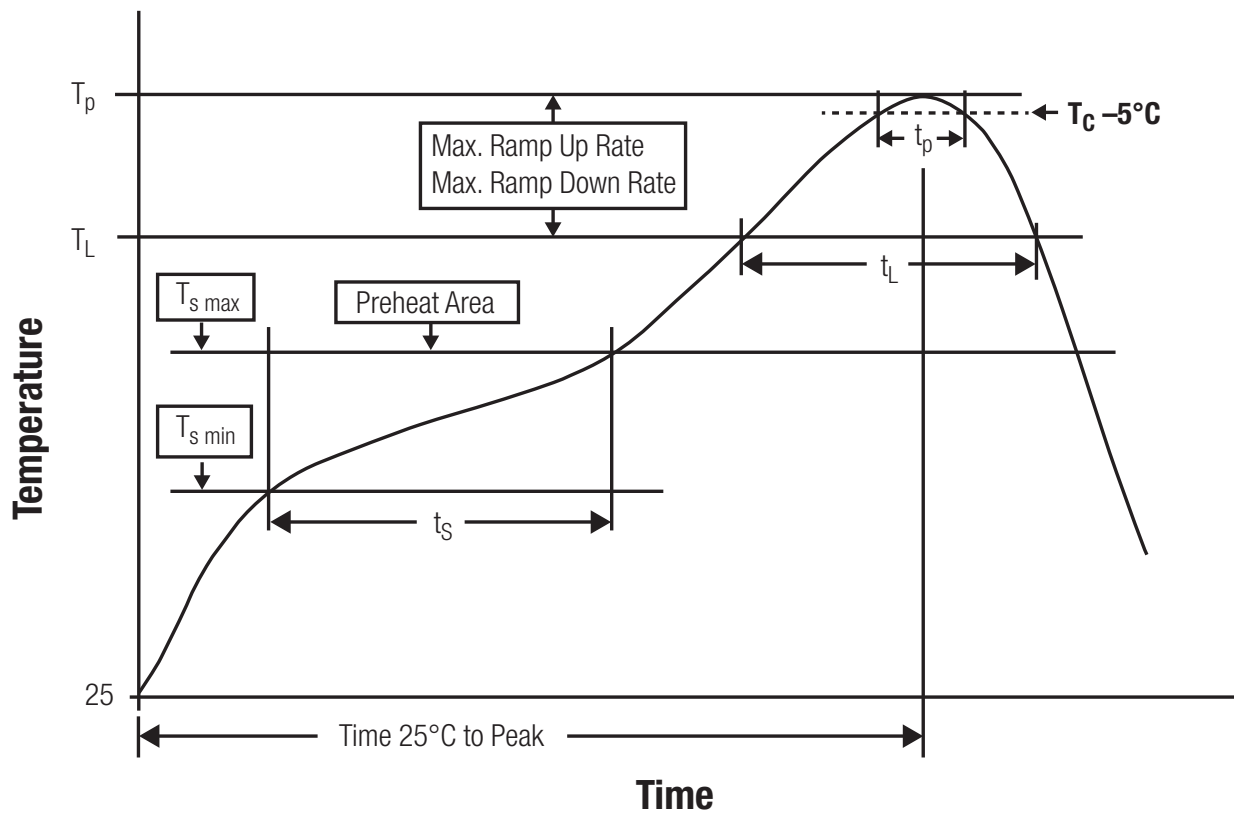


Figure 23: Reflow soldering profile

After reflow soldering, visually inspect the board to confirm proper alignment

22.2.2. Cleaning

Do not clean the product. Any residue cannot be easily removed by washing. Use a "no clean" soldering paste and do not clean the board after soldering.

- Do not clean the product with water. Capillary effects can draw water into the gap between the host PCB and the module, absorbing water underneath it. If water is trapped inside, it may short-circuit adjoining pads. The water may also destroy the label and ink-jet printed text on it.
- Cleaning processes using alcohol or other organic solvents may draw solder flux residues into the housing, which won't be detected in a post-wash inspection. The solvent may also destroy the label and ink-jet printed text on it.
- Do not use ultrasonic cleaning as it will permanently damage the part, particularly the crystal oscillators.

22.2.3. Potting and coating

- If the product is potted in the customer application, the potting material might shrink or expand during and after hardening. Shrinking could lead to an incomplete seal, allowing contaminants into the component. Expansion could damage components. We recommend a manual inspection after potting to avoid these effects.
- Conformal coating or potting results in loss of warranty.
- The RF shield will not protect the part from low-viscosity coatings and potting. An undefined amount of coating and potting will enter inside the shielding.
- Conformal coating and potting will influence the parts of the radio front end and consequently influence the radio performance.
- Potting will influence the temperature behaviour of the device. This might be critical for components with high power.

22.2.4. Other notations

- Do not attempt to improve the grounding by forming metal strips directly to the EMI covers or soldering on ground cables, as it may damage the part and will void the warranty.
- Always solder every pad to the host PCB even if some are unused, to improve the mechanical strength of the module.
- The part is sensitive to ultrasonic waves, as such do not use ultrasonic cleaning, welding or other processing. Any ultrasonic processing will void the warranty.

22.3. ESD handling

This product is highly sensitive to electrostatic discharge (ESD). As such, always use proper ESD precautions when handling. Make sure to handle the part properly throughout all stages of production, including on the host PCB where the module is installed. For ESD ratings, refer to the module series' maximum ESD section. For more information, refer to the relevant chapter 2. Failing to follow the aforementioned recommendations can result in severe damage to the part.

- the first contact point when handling the PCB is always between the local GND and the host PCB GND, unless there is a galvanic coupling between the local GND (for example work table) and the host PCB GND.
- Before assembling an antenna patch, connect the grounds.
- While handling the RF pin, avoid contact with any charged capacitors and be careful when contacting any materials that can develop charges (for example coaxial cable with around 50-80 pF/m, patch antenna with around 10 pF, soldering iron etc.)
- Do not touch any exposed area of the antenna to avoid electrostatic discharge. Do not let the antenna area be touched in a non ESD-safe manner.
- When soldering, use an ESD-safe soldering iron.

22.4. Safety recommendations

It is your duty to ensure that the product is allowed to be used in the destination country and within the required environment. Usage of the product can be dangerous and must be tested and verified by the end user. Be especially careful of:

- Use in areas with risk of explosion (for example oil refineries, gas stations).
- Use in areas such as airports, aircraft, hospitals, etc., where the product may interfere with other electronic components.

It is the customer's responsibility to ensure compliance with all applicable legal, regulatory and safety-related requirements as well as applicable environmental regulations. Disassembling the product is not allowed. Evidence of tampering will void the warranty.

- Compliance with the instructions in the product manual is recommended for correct product set-up.
- The product must be provided with a consolidated voltage source. The wiring must meet all applicable fire and security prevention standards.
- Handle with care. Avoid touching the pins as there could be ESD damage.

Be careful when working with any external components. When in doubt consult the technical documentation and relevant standards. Always use an antenna with the proper characteristics.



Würth Elektronik eiSos radio modules with high output power of up to 500 mW generate a large amount of heat while transmitting. The manufacturer of the end device must take care of potentially necessary actions for his application.

23. Product testing

23.1. Würth Elektronik eiSos in-house production tests

To achieve a high quality standard, Würth Elektronik eiSos follows a philosophy of supplying fully tested radio modules. At the end of the production process, every unit undergoes an optical inspection. Here the quality of soldering, edge castellation and edge milling is monitored.

If this has been passed, the radio modules are handed over to the automatic test equipment for the electrical characterization. This includes:

- Voltage and current tests to ensure proper electrical performance
- RF characteristics (frequency, spectrum, TX power) measurement and calibration
- Radio communication tests
- Firmware and serial number programming
- Host interface communication tests

The automated testing process is logged for internal quality control. The gained measurement data of each unit is analysed to detect defective parts and investigate the corresponding root cause. Defective radio modules are discarded, in order to guarantee a 100% failure-free delivery to customers.

23.2. EMS production tests

The rigorous in-series production testing ensures that EMS don't need to duplicate firmware tests or measurements. This streamlines the process and eliminates the need for additional testing over analogue and digital interfaces during device production. When it comes to device testing, the ideal focus should be on module assembly quality:

- All module pins are soldered properly on the base PCB
- There are no short circuits
- The mounting process did not damage the module
- The communication between host and radio module is working
- The antenna is connected properly

Simple "Go/No go" tests, like checking the RSSI value, give already a hint if the power supply and antenna have been connected properly.

In addition to such standard testing procedures, radio module integrators have the flexibility to perform additional dedicated tests to thoroughly evaluate the device. Specific tests they can consider are:

- Measure module current consumption in a specified operating state. Deviations from expected results (compared to a "Golden Device") can signal potential issues.

- Perform functional tests, including communication checks with the host controller and verification of interfaces.
- Assess fundamental RF characteristics (modulation accuracy, power levels, spectrum). Verify that the device meets expected performance standards.

24. Physical specifications

24.1. Dimensions

Dimensions
12 x 8 x 2 mm

Table 18: Dimensions

24.2. Weight

Weight
<1 g

Table 19: Weight

24.3. Module drawing

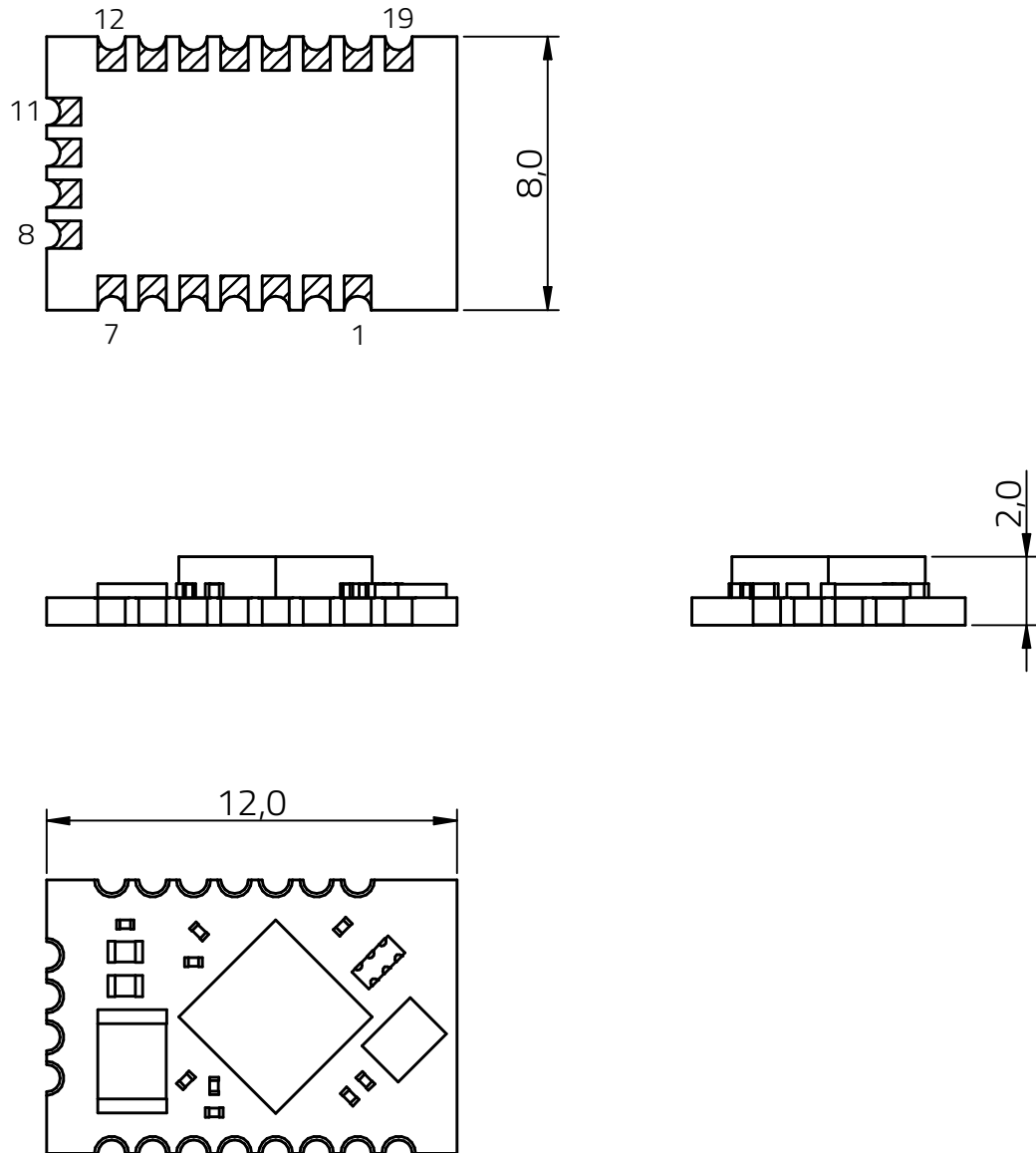


Figure 24: Module dimensions [mm]

24.4. Footprint

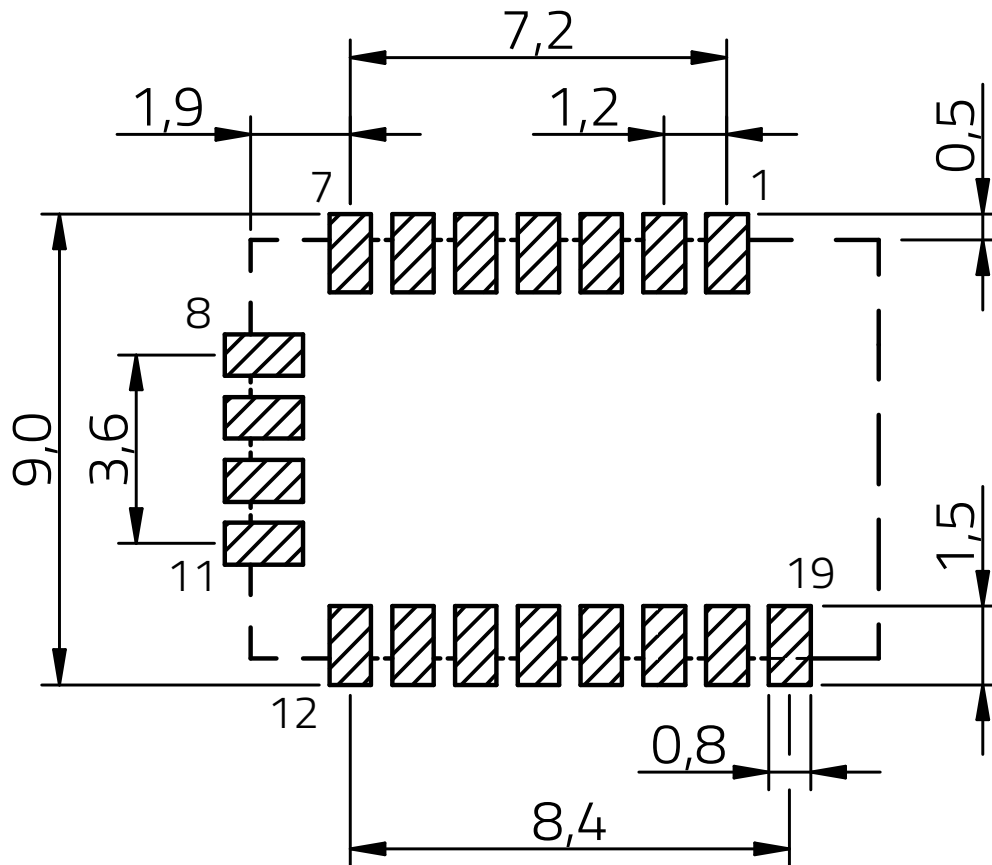


Figure 25: Footprint and dimensions [mm]

The following points have to be considered:

- To avoid the risk of short circuits, a minimum clearance of at least 14 mm between the opposing pad rows has to be maintained. No routing on the top layer of a carrier PCB (i.e. "under" the module) shall be performed.
- For the module variant with integrated antenna, the marked corner area of 7.3 x 13.8 mm has to be kept free from metal, on any layer.
- The four bottom side pads are optional for the firmware update using JTAG. They can be left open when JTAG update is not needed in the customer's application.

25. Marking

25.1. Lot number

The 15 digit lot number is printed in numerical digits as well as in form of a machine readable bar code. It is divided into 5 blocks as shown in the following picture and can be translated according to the following table.

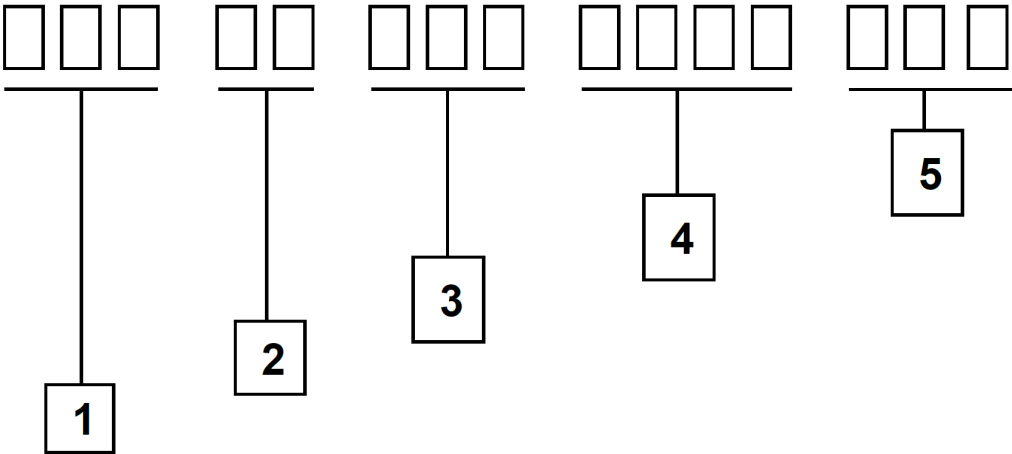


Figure 26: Lot number structure

Block	Information	Example(s)
1	eiSos internal, 3 digits	438
2	eiSos internal, 2 digits	01
3	Radio module hardware version, 3 digits	V2.4 = 024, V12.2 = 122
4	Date code, 4 digits	1703 = week 03 in year 2017, 1816 = week 16 in year 2018
5	Radio module firmware version, 3 digits	V3.2 = 302, V5.13 = 513

Table 20: Lot number details

As the user can perform a firmware update the printed lot number only shows the factory delivery state. The currently installed firmware can be requested from the module using the corresponding product specific command. The firmware version as well as the hardware version are restricted to show only major and minor version not the patch identifier. Block 5 is not applicable for products without firmware.

25.2. General labeling information

Labels of Würth Elektronik eiSos radio modules include several fields. Besides the manufacturer identification, the product's *WE* order code, serial number and certification information are placed on the label. In case of small labels, additional certification marks are placed on the label of the reel.

The information on the label are fixed. Only the serial number changes with each entity of the radio module. For Tarvos-e the label is as follows:

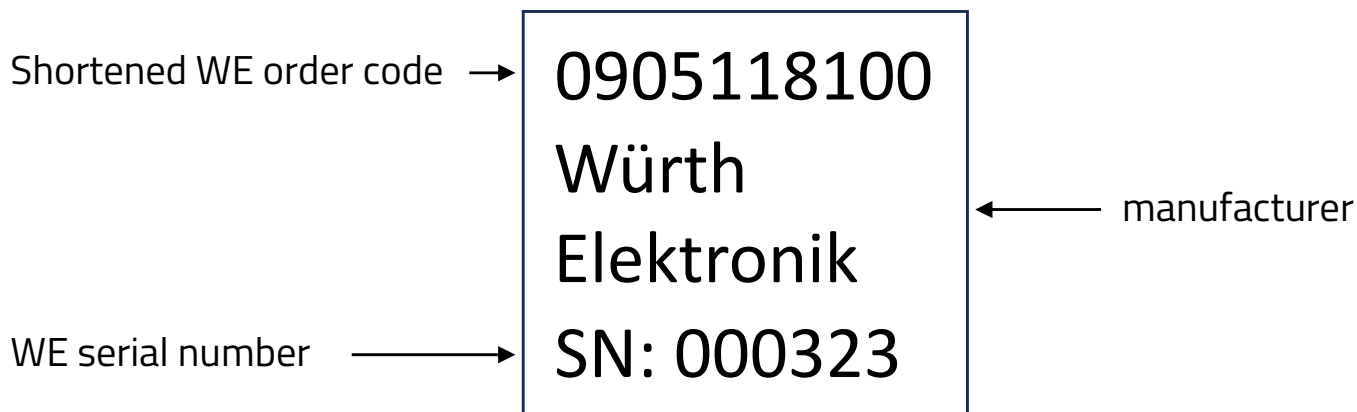


Figure 27: Label of the Tarvos-e

26. Information for explosion protection

In case the end product should be used in explosion protection areas the following information can be used:

- The module itself is unfused.
- The maximum output power of the module is 14 dBm.
- The total amount of capacitance of all capacitors is 45.6 μF .
- The total amount of inductance of all inductors is 6.81 μH .

27. Regulatory compliance information

27.1. Important notice EU

The use of RF frequencies is limited by national regulations. The Tarvos-e has been designed to comply with the RED directive 2014/53/EU of the European Union (EU).

The Tarvos-e can be operated without notification and free of charge in the area of the European Union. However, according to the RED directive, restrictions (e.g. in terms of duty cycle or maximum allowed RF power) may apply.

27.2. Important notice UKCA

The UK's government has laid legislation to continue recognition of current EU requirements for a range of product regulations, including the CE marking. The Radio Equipment Regulation 2017/1206 is within the scope of this announcement, among others.

Consequently, the Tarvos-e can be sold and utilized in the UK with the CE marking, without the need of UKCA declaration of conformity or UKCA marking.

Source: <https://www.gov.uk/guidance/ce-marking>

27.3. Conformity assessment of the final product

The Tarvos-e is a subassembly. It is designed to be embedded into other products (products incorporating the Tarvos-e are henceforward referred to as "final products").

It is the responsibility of the manufacturer of the final product to ensure that the final product is in compliance with the essential requirements of the underlying national radio regulations.

The conformity assessment of the subassembly Tarvos-e carried out by Würth Elektronik eiSos does not replace the required conformity assessment of the final product.

27.4. Exemption clause

Relevant regulation requirements are subject to change. Würth Elektronik eiSos does not guarantee the accuracy of the before mentioned information. Directives, technical standards, procedural descriptions and the like may be interpreted differently by the national authorities. Equally, the national laws and restrictions may vary with the country. In case of doubt or uncertainty, we recommend that you consult with the authorities or official certification organizations of the relevant countries. Würth Elektronik eiSos is exempt from any responsibilities or liabilities related to regulatory compliance.

Notwithstanding the above, Würth Elektronik eiSos makes no representations and warranties of any kind related to their accuracy, correctness, completeness and/or usability for customer applications. No responsibility is assumed for inaccuracies or incompleteness.

27.5. EU Declaration of conformity



EU DECLARATION OF CONFORMITY

Radio equipment: 2609051181000

The manufacturer: Würth Elektronik eiSos GmbH & Co. KG
Max-Eyth-Straße 1
74638 Waldenburg

This declaration of conformity is issued under the sole responsibility of the manufacturer.

Object of the declaration: 2609051181000

The object of the declaration described above is in conformity with the relevant Union harmonisation legislation Directive 2014/53/EU and 2011/65/EU with its amending Annex II EU 2015/863. Following harmonised norms or technical specifications have been applied:

EN 300 220-1 V3.1.1 (2017-02)
EN 300 220-2 V3.1.1 (2017-02)
EN 301 489-1 V2.2.3 (2019-11)
EN 301 489-3 V2.1.1 (2019-03)
EN 62311 : 2008
EN 62368-1: 2014/AC: 2015/A11: 2017

i.A. G. Eschardt

Trier, 27th of February 2025
Place and date of issue

28. Important notes

The following conditions apply to all goods within the wireless connectivity and sensors product range of Würth Elektronik eiSos GmbH & Co. KG:

General customer responsibility

Some goods within the product range of Würth Elektronik eiSos GmbH & Co. KG contain statements regarding general suitability for certain application areas. These statements about suitability are based on our knowledge and experience of typical requirements concerning the areas, serve as general guidance and cannot be estimated as binding statements about the suitability for a customer application. The responsibility for the applicability and use in a particular customer design is always solely within the authority of the customer. Due to this fact, it is up to the customer to evaluate, where appropriate to investigate and to decide whether the device with the specific product characteristics described in the product specification is valid and suitable for the respective customer application or not. Accordingly, the customer is cautioned to verify that the documentation is current before placing orders.

Customer responsibility related to specific, in particular safety-relevant applications

It has to be clearly pointed out that the possibility of a malfunction of electronic components or failure before the end of the usual lifetime cannot be completely eliminated in the current state of the art, even if the products are operated within the range of the specifications. The same statement is valid for all software source code and firmware parts contained in or used with or for products in the wireless connectivity and sensor product range of Würth Elektronik eiSos GmbH & Co. KG. In certain customer applications requiring a high level of safety and especially in customer applications in which the malfunction or failure of an electronic component could endanger human life or health, it must be ensured by most advanced technological aid of suitable design of the customer application that no injury or damage is caused to third parties in the event of malfunction or failure of an electronic component.

Best care and attention

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User manual Tarvos-e

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17. Classification reflow soldering profile, Note: refer to IPC/JEDEC J-STD-020E . .

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21. CRC8 Test Vectors

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A. Additional CRC8 Information

This Annex gives an example CRC8 implementation and test vectors.

A.1. Example CRC8 Implementation

```
#include <stdint.h>

uint8_t Get_CRC8(uint8_t * bufP, uint16_t len)
{
    uint8_t crc = 0x00;
    for (uint16_t i = 0; i < len; i++)
    {
        crc ^= bufP[i];
    }
    return crc;
}
```

Code 1: Example CRC8 Implementation

A.2. CRC8 Test Vectors

Input data	Data length	Resulting CRC8
Null	0	0x00
0x02 0x01 0x00 0x00	4	0x03
0x02 0x87 0x01 0x00 0x16	5	0x92
0x02 0x04 0x04 0x00 0x41 0x42 0x43 0x44	8	0x06
0x02 0x88 0x07 0x00 0x00 0x55 0x00 0x00 0xDA 0x18 0x00	11	0x1A

Table 21: CRC8 Test Vectors

B. Example code for host integration

The following code is an example implementation of a function to transmit data using a 1 byte length field in the command frame. For demonstration reasons, the Tarvos-III has been taken. The full function codes of all radio modules are available in the Wireless Connectivity SDK (www.we-online.com/wco-SDK).

```
#define CMD_PAYLOAD_MAX 224
typedef struct {
    uint8_t Stx;
    uint8_t Cmd;
    uint8_t Length;
    uint8_t Data[CMD_PAYLOAD_MAX+1]; /* +1 for CRC8 */
} CMD_Frame_t;
#define CMD_OFFSET_TO_DATAFIELD 3
#define CMD_OVERHEAD (CMD_OFFSET_TO_DATAFIELD+1)

bool TarvosIII_Transmit(uint8_t *PayloadP, uint8_t length)
{
    /* fill request message with STX, command byte and length field */
    CMD_Frame_t CMD_Frame;
    CMD_Frame.Stx = CMD_STX; /* 0x02 */
    CMD_Frame.Cmd = TarvosIII_CMD_DATA_REQ; /* 0x00 */
    CMD_Frame.Length = length;

    /* fill request message with user payload */
    memcpy(CMD_Frame.Data, PayloadP, length);

    /* fill request message with CRC8 */
    CMD_Frame.Data[CMD_Frame.Length] = Get_CRC8(&CMD_Frame, CMD_Frame.Length +
        CMD_OFFSET_TO_DATAFIELD);

    /* transmit full message via UART to radio module */
    UART_SendBytes(&CMD_Frame, (CMD_Frame.Length + CMD_OVERHEAD));

    /* wait for response message from radio module */
    return UART_Wait_for_Response(CMD_WAIT_TIME, TarvosIII_CMD_DATA_CNF, CMD_Status_Success, true)
        ;
}
```

Code 2: Example function implementation for radio modules with 1 byte length field

**Contact**

Würth Elektronik eiSos GmbH & Co. KG
Division Wireless Connectivity & Sensors

Max-Eyth-Straße 1
74638 Waldenburg
Germany

Tel.: +49 651 99355-0
Fax.: +49 651 99355-69
www.we-online.com/wireless-connectivity

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